# **Programmable Controller**

FIBER SENSORS

Related Information ☐ General terms and conditions...... F-3







RoHS compliance

# Automation Controls + Information Panasonic PLCs also control information

# **CONTROL MACHINERY AND FACILITIES**

Along with operation speed and capacity, delivers ease of use for design, production, and maintenance

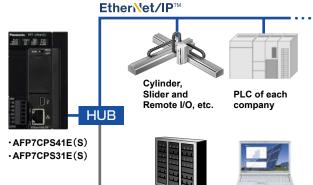
Models with built-in Ethernet ports add functionality to

Easy connection with all kinds of robots and PLCs enables control and communication.

\*EtherNet/IP is a trademark of ODVA, Inc.

EtherNet/IP\* compatibility **Cassette system** 

РС

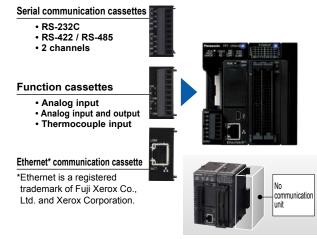


Server

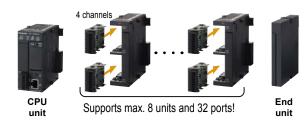
TCP/IP

# reduces unit cost and footprint

With ease and at low cost, extend the serial communication and analog functionality of CPU units.



Moreover, when used as a serial communication unit, expansion to as many as 35 channels is possible. Reduces cost and footprint.



# Applications Software

WIRE-SAVING UNITS WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS

STATIC CONTROL

HUMAN MACHINE INTERFACES

MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

FNFRGY

DEVICES LASER MARKERS

Program Transfer Others

FP-X0

FP0R FPΣ FP-X

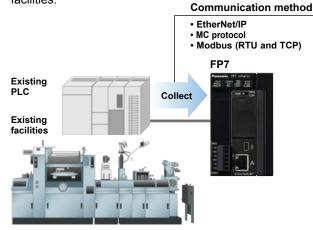
FP2SH

### **COLLECT WORK SITE INFORMATION**

The FP7 can collect voltage, electric power, temperature, production output, alarm notifications, and other information

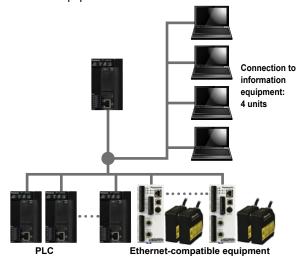
Equipped to deal with any protocol, it can be installed in existing facilities to enable collection of information.

To enable information collection, because the **FP7** can deal with any protocol for Ethernet / serial communications, the **FP7** can be installed in existing facilities.



### Communicating with up to 220 equipment units

Communicate easily with many units, including automation control equipment such as PLCs and information equipment such as PCs.



Connection to automation control equipment: 216 units (Simultaneous communication: 16 units)

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AREA SENSORS

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PRESSURE / FLOW SENSORS INDUCTIVE PROXIMITY

PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

### PLC

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ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

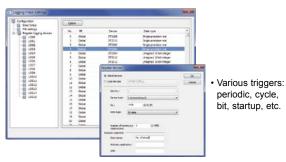
UV CURING

### LOGS COLLECTED INFORMATION

The FP7 securely stores and carries out log management of collected information assets

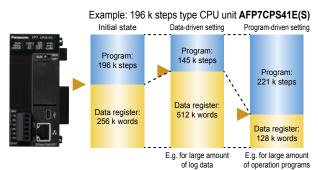
### Easy multiple concurrent logging

Logging set up is done via the configuration screen. Moreover, it is possible to keep up to 16 files concurrently active.



Use program and data register sharing to resolve data space shortage.

No need repurchase expensive upgrade models.



### Protection of log data

Diagnosis of rewrite life of SD memory card helps protect valuable information assets.

Note: Diagnosis possible when Panasonic industrial-spec SD memory cards are used.



### Reference value: for 196 k steps type CPU unit (Note)

Program	234 k	221 k	196 k	145 k	52 k
	steps	steps	steps	steps	steps
Data	64 k	128 k	256 k	512 k	976 k
register	words	words	words	words	words

Note: For data register (DT), data up to 256 k words can be backed up.

Contware
Program Transfer
TTUTIOTCI
Others

Applications

### FP7

FP-X0

FP0R

FPΣ FP-X

FP2SH

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> AREA SENSORS

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SENSORS PARTICULAR USE SENSORS

> SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS

> STATIC CONTROL DEVICES

LASER MARKERS

PL

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Applications
PLC
Software
Program
Transfer

Others

FP7
FP-X0
FP0R
FP2
FP-X
FP2SH

FP-e

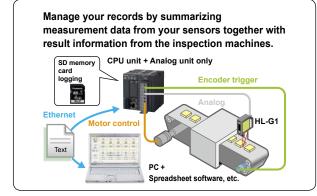
### INFORMATION CAN BE TRANSFERRED TO DIFFERENT TYPES OF MEDIA

FP7 transmits information to PC, server or the cloud, etc.

# Information can be transferred to different types of media

Allows the PC to read the logging data in the **FP7**'s SD memory card and to write setting values and other parameters.





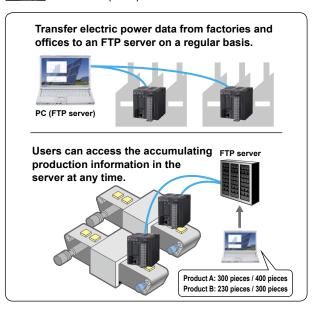
### FTP(S) client function (SSL-compatible)

The **FP7** can generate and write data files to an FTP server on a PC as well as read data files from the FTP server.

The sessions use SSL, protecting IDs and passwords.

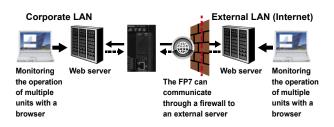


Data collection, data viewing and data writing from multiple units in the form of files



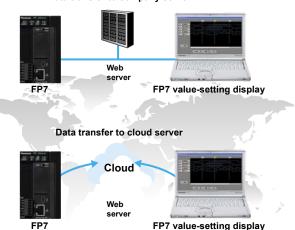
### HTTP(S) client function (SSL-compatible)

Transfer data from the **FP7** to a web server for easy viewing with a browser. Send and receive data from multiple **FP7** units on a schedule controlled by the **FP7**. Communicate both inside the firewall on an intranet and outside the firewall to the wider world through the Internet.



Allow users from around the world to access the current state of their equipment.

### Data transfer to company server



### **CHECK INFORMATION AT YOUR FINGERTIPS**

Data collected by the FP7 can be displayed in a web browser Via smartphone or PC, it's easy to check the current state of the work site

### Web server function

Monitor and control the **FP7** without the use of custom software. Users can check the accumulated data in the **FP7** with a browser.



Operation can be monitored with a browser and control instructions can be sent from a browser.

### 1. Check out status of greenhouse / food processing

With data always at hand, there's no need to go to the work site to check indoor temperature and humidity or the operation of pumps, heaters, and other equipment.



# 2. Operational status and production log management for production line

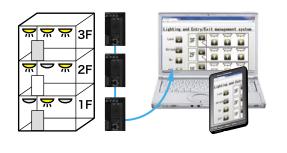
Operational status of the production line can be checked and traceability production control can be carried out.

Current production line information can be collected and displayed on Web interface.



### 3. Building lighting / entry and exit management

Through a web interface, it is possible to check the status of lighting in buildings and apartments, and to building entries and exits.

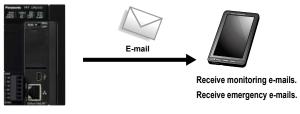


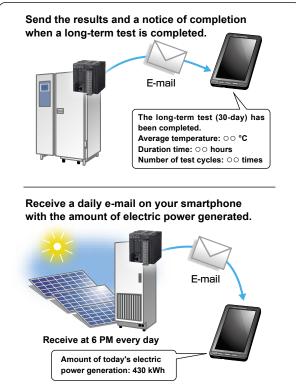
### Information updates viewable in e-mail.

The managers can receive and view e-mailed malfunction notifications and daily reports of equipment operations.

### E-mail sending function (SSL-compatible)

Use instructions and timings controlled by the **FP7** to send e-mails on a pre-set schedule or when a pre-set condition changes in the PLC. The e-mails can have data files attached and communication is SSL-capable to protect the e-mails.





For more information on web server function, please see this catalog.



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INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS WIRE-SAVING

SYSTEMS

MEASUREMENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

### PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Applications

Software

Program Transfer

Others

### FP7

FP-X0

FP0R FPΣ

FP-X

FP2SH

LASER

PHOTOELECTRIC SENSORS

MICRO PHOTOELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY **SENSORS PARTICULAR** USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS STATIC CONTROL

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# Applications Software Program Transfer Others

FP7
FP-X0
FP0R
FPΣ
FP-X
FP2SH
FP-e

### **MAINTENANCE**

### Historical archiving of program changes

Operational events to CPU and program editing events are logged. Useful for debugging and tracing the cause of malfunctions

Date of occurrence	Time	Trigger
2014/11/21	14:05:35	Power: ON
2014/11/21	14:07:13	Open cover
2014/11/21	14:20:25	Insert SD memory card.
2014/11/21	14:30:19	Close cover
2014/11/21	14:31:00	Download program
2014/11/21	14:33:10	Switch operation mode to RUN
2014/11/21	14:35:12	Program edition during RUN
2014/11/21	14:35:32	Upload program
2014/11/21	14:40:07	Power: OFF

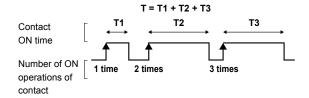
Note: Data logs are virtual.

### Set a maintenance schedule that is based on an automatic measurement of contact switching cycles or overall ON time

Service intervals can be timed according to logged contact switching cycles, and power-on duration, thus enabling preventive maintenance of equipment and peripheral equipment.

Input contacts (X): Automatically measures and logs total ON times and number of ON operations of connected sensors.

Output contacts (Y): Automatically measures and logs total ON times and number of ON operations of connected actuators. The maintenance schedules for relays, motors, etc. can be optimized.

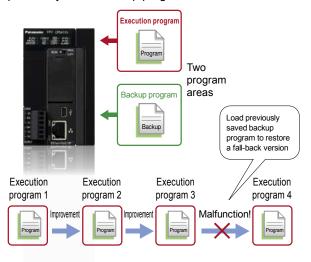


### Records the PLC's ON time

Equipment operating time can be estimated. You can decide which equipment to give priority to reactivate if more than one item of equipment is idle.

### The built-in program backup allows users to immediately recover factory default conditions

The CPU unit can store two programs. In the event of fault, no SD memory card is needed to return to a previously saved backup program.



### No need to replace a battery by data back up function without battery

Equipment maintenance tasks are reduced because battery is not required. And, to save power, equipment can be switched off without hesitation.



Item	Without battery	With battery		
Program holding	Yes	Yes		
Data register holding (Note 1)	Yes	Yes		
Clock / calendar operation	No (Note 2)	Yes		

Notes: 1) Data register (DT) of up to 256 k words can be backed up. 2) Clock / calendar operation can be held for about a week if

the equipment is switched off. (Allow at least 30 minutes of equipment ON time.)

The built-in clock / calendar function can be adjusted via Ethernet. Adjustment at power start up allows the battery-free system to be configured.

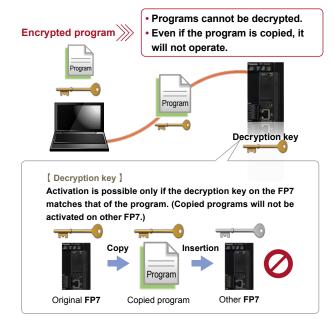
### **SECURITY AND COMPACT DESIGN**

### Program level encryption ensures protection against copying program code

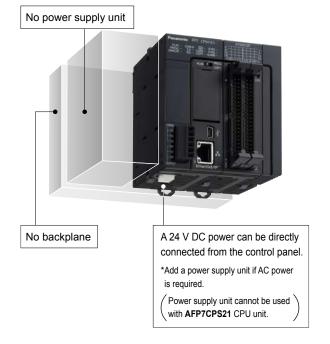
Security enhanced type

Any attempt to copy the installed equipment's program into a newly purchased FP7 will fail due to an unmatched decryption key, resulting in the equipment becoming inoperable.

Note: When exporting to China, please use a CPU unit that does not have an encryption function.



### Without the requirement of a power supply unit or backplane, you can reduce the cost and footprint of your PLC configuration



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AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS INDUCTIVE PROXIMITY

**SENSORS** PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASUREMENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

# A high performance PLC with a small footprint



Applications

Software

Program Transfer Others

FP-X0

FP0R

FPΣ

FP-X

FP2SH

LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

CURING SYSTEMS

Applications

Software

Program Transfer Others

FP-X0 FP0R

FPΣ

FP-X

FP2SH FP-e

### **LINEUP**

**CPU** units Standard model

Standard model

Security enhanced type





EtherNet/IP™

AFP7CPS41ES



Etheri\et/IP™

AFP7CPS31ES



AFP7CPS31S





\*Included with CPU unit and Expansion slave unit

End unit

**Expansion** units



Expansion master unit AFP7EXPM



Expansion slave unit **AFP7EXPS**  **Power supply** units



AC power supply unit AFP7PSA1



Add-on cassettes

Communication cassettes



RS-232C 1 channel AFP7CCS1



RS-232C 2 channels AFP7CCS2



RS-422 / RS-485 1 channel AFP7CCM1



RS-422 / RS-485 2 channels AFP7CCM2



RS-232C 1 channel RS-485 1 channel AFP7CCS1M1

Ethernet 1 channel AFP7CCET1

**Function cassettes** 



Analog input AFP7FCAD2



Analog input and output AFP7FCA21



Thermocouple input AFP7FCTC2

Serial communication unit



AFP7NSC

\*Communication cassette is sold separately.

\*Dedicated serial communication.

**Digital input** and output units

Input units



Terminal block 16 points, 12 to 24 V DC input AFP7X16DW



MIL connector 32 points, 24 V DC input AFP7X32D2



MIL connector 64 points, 24 V DC input AFP7X64D2

**Output units** 



Terminal block 16 points, relay output AFP7Y16R



Terminal block 16 points, transistor output (sink) AFP7Y16T



MIL connector 32 points, transistor output (sink) AFP7Y32T



MIL connector 64 points, transistor output (sink) AFP7Y64T



Terminal block 16 points, transistor output (source) AFP7Y16P



MIL connector 32 points, transistor output (source) AFP7Y32P



MIL connector 64 points, transistor output (source) AFP7Y64P

Input and output units



MIL connector 32 points, 24 V DC input 32 points, transistor output (sink) AFP7XY64D2T



MIL connector 32 points, 24 V DC input 32 points, transistor output (source) AFP7XY64D2P

### LINEUP

# Analog input and output units

Input units





High-speed and high-accuracy type, 4 points, voltage and current AFP7AD4H





# Temperature input units

Thermocouple multiple analog input unit

Resistance temperature detector input unit



Thermocouple input and analog input AFP7TC8



Resistance temperature detector input AFP7RTD8

# Multi input and output units



Input: 16 points (DC / Counter etc.)
Output: 16 points (Transistor / PWM etc.)
AFP7MXY32DWD



Positioning type
Input: 16 points (DC / Counter etc.)
Output: 16 points (Transistor / Positioning etc.)
AFP7MXY32DWDH

High-speed counter units



2 channels
16 MHz (for 2-phase, 4-multiple)
4 MHz (for individual input)
AFP7HSC2T



4 channels 16 MHz (for 2-phase, 4-multiple) 4 MHz (for individual input) AFP7HSC4T

# Positioning units

Pulse train



Transistor output 2 axes 500 kpps AFP7PP02T



Transistor output 4 axes 500 kpps AFP7PP04T





Line driver output 4 axes 4 Mpps AFP7PP04L

# Pulse output units



Transistor output 2 axes 500 kpps AFP7PG02T



Transistor output 4 axes 500 kpps AFP7PG04T





Line driver output 4 axes 4 Mpps

AFP7PG04L

# Motion control



Real axis 16 axes Virtual axis 8 axes AFP7MC16EC



Real axis 32 axes
Virtual axis 16 axes
AFP7MC32EC



# PHLS (remote I/O) units

PHLS master unit



AFP7PHLSM

PHLS slave units Input type



Compact type (e-CON) 8 points, 24 V DC input AFPRP2X08D2E



Compact type
(Connector-type terminal block)
16 points, 24 V DC input
AFPRP2X16D2



Standard type
(Screw-type terminal block)
8 points, 24 V DC input
AFPRP1X08D2



Standard type
(Screw-type terminal block)
16 points, 24 V DC input

AFPRP1X16D2

PHLS slave units Output type



Compact type
(Connector-type terminal block)
16 points, transistor output (sink)

AFPRP2Y16T



Compact type (Connector-type terminal block) 4 points, relay output AFPRP2Y04R



Standard type (Screw-type terminal block) 16 points, transistor output (sink) AFPRP1Y16T

PHLS slave units Input and output types



Compact type (Connector-type terminal block) 8 points, 24 V DC input 8 points, transistor output (sink) AFPRP2XY16D2T



Standard type (Screw-type terminal block) 8 points, 24 V DC input 8 points, transistor output (sink) AFPRP1XY16D2T FIBER SENSORS

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PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS SENSOR OPTIONS

MPLE

UNITS

WIRE-SAVING SYSTEMS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

> MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Applications

Software

Program Transfer Others

FP7

FP-X0 FP0R

FPΣ FP-X

FP2SH

LASER

PHOTO-ELECTRIC SENSORS MICRO

AREA SENSORS

CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS

SENSOR OPTIONS SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS MEASURE-

MENT SENSORS STATIC CONTROL DEVICES

LASER MARKERS

HUMAN MACHINE INTERFACES ENERGY MANAGEMENT

FA COMPONENTS

MACHINE VISION SYSTEMS

CURING SYSTEMS

Applications
PLC
Software
Program
Transfer

FP7

Others

FP0R FPΣ FP-X

FP2SH FP-e

### **CPU UNITS**



### Compact design and class-leading high performance

### The function is expanded easily with cassette interface

The function extension is possible without increasing the width of the unit.

The cassettes support RS-232C, RS-422 and RS-485 for series communication, Ethernet communication and various analog input and output.

# High-capacity SD (SDHC) memory cards of up to 32 GB are supported

Enables large storage for log data \*except for AFP7CPS21

### **High performance**

Scan times of 20  $\mu$ s or less and minimum execution times of 1 ms at 60 k steps. System is designed so that frequent Ethernet communication has almost no effect on processing speed.

### All communications ports are safely isolated

Confidently use any port - RS-422 / RS-485 and LAN ports, as well as USB and RS-232C ports - each is isolated.

# High function types, increased security (encryption), are available

Note: When exporting to China, please use a CPU unit that does not have an encryption function.

### SPECIFICATIONS

# Control specifications Item

	Memory selection pattern (Note 2)	1		2 3 (Fac defa			4		5
Memory capacity	Program (steps) (Note 3)	234,000	22	21,500	1,500 196,0		144,50	0	51,500
	Data register (words) (Note 3)	65,536	13	31,072 262,1		,144 524,28		8	999,424
	Number of max. program block (PB)	468		443		2	289		103
Item		AFP7CPS31E(S) / AFP7CPS31(S) (Note 1)							
	Memory selection pattern (Note 2)	1 (Factor default)				3			4
Memory	Program (steps) (Note 3)	121,500	)	96,000		64	,000,		32,000
capacity	Data register (words) (Note 3)	131,072	131,072 262		44 42		5,984	5	589,824
	Number of max. program block (PB)	243	3 192		2		28		64
Item		AFP7CPS21							
Memory selection pattern (Note 2)		1 (Factory default)			2				

AFP7CPS41E(S) (Note 1)

	Item	AFP7CPS21			
	Memory selection pattern (Note 2)	1 (Factory default)	2		
Memory	Program (steps) (Note 3)	64,000	32,000		
capacity	Data register (words) (Note 3)	131,072	262,144		
	Number of max. program block (PB)	128	64		

Notes: 1) Products with an "S" at the end of a part number have the encryption function.

- The factory default setting is pattern 3 for AFP7CPS41E(S) and pattern 1 for AFP7CPS31E(S), AFP7CPS31(S) and AFP7CPS21
- For data register (DT), data up to 262,144 words can be backed up.

Item (Note 1)	AFP7CPS41E(S) / AFP7CPS31E(S) / AFP7CPS31(S) / AFP7CPS21
CE marking directive compliance	EMC Directive, RoHS Directive
Programming method	Relay symbol method
Control method	Cyclic operation method
Program memory	Built-in flash ROM (no backup battery required)
Operation speed	Basic instruction: Min. 11 ns/step (AFP7CPS21: 14 ns/step)
External input (X) / output (Y)	8,192 points (Note 2) / 8,192 points (Note 2)
Internal relays (R)	32,768 points
System relays (SR)	Indicate operation status of various relays is shown.
Link relays (L)	16,384 points
Timers (T)	4,096 points: Timer capable of counting (units: 10 $\mu s,$ 1 ms, 10 ms, 100 ms or 1 sec.) × 4,294,967,295
Counters (C)	1,024 points, Counter capable of counting 1 to 4,294,967,295
Link data registers (LD)	16,384 words
System data registers (SD)	Internal operation status of various registers is shown.
Index registers (I0 to IE)	15 long words / With switching function
Master control relay (MCR)	Unlimited
Number of labels (LOOP)	Max. 65,535 points for each program block (PB)
Differential points	Unlimited
Number of step ladders	Unlimited
Number of subroutines	Max. 65,535 points for each program block (PB)
Number of interrupt programs	1 periodical interrupt program
SD memory card function	SDHC memory cards of up to 32 GB are usable. *except for AFP7CPS21
Constant scan	Available (0 to 125 ms)
Clock / calendar (Note 3)	Year (last two digits), month, day, hours (24-hour display) minutes, seconds, day of week
Battery life	$3.3\mathrm{years}$ or more (at +25 °C +77 °F) (when no power is supplied) *except for AFP7CPS21
Security function (Note 4)	Password / Restricted distribution / Read disable setting / Encryption
PLC link function	Max. 16 units, link relays: 1,024 points, link registers: 128 words. (Data transfer and remote programming are not supported) (Link area allocation is switchable between the first and the second half)

 $\label{Notes:1} \textbf{Notes: 1) Products with an "S"} at the end of a part number have the encryption function.$ 

- 2) Hardware configuration governs the actually usable number of I/O points. When I/O points are not actually used, usable as internal relays.
- 3) Precision of calendar; At 0 °C +32 °F, 95 sec. or less error per month, at +25 °C +77 °F, 15 sec. or less error per month, at +55 °C +131 °F, 130 sec. or less error
- 4) Encryption can be used for AFP7CPS41ES, AFP7CPS31ES and AFP7CPS31S.

### **SPECIFICATIONS**

### **COM** port communication specifications

Item	Specifications			
Interface	RS-232C, three-wire system, 1 channel (Note)			
Transmission distance	15 m 49.213 ft			
Transmission speed	300, 600, 1,200, 2,400, 4,800, 9,600, 19,200, 38,400, 57,600, 115,200, 230,400 bits/sec.			
Communication method / Synchronous method	Half-duplex system / Start-stop synchronization system			
	Stop bit: 1 bit / 2 bits			
	Parity: none / odd / even			
Transmission format	Data length: 7 bits / 8 bits			
	Start code: with STX / without STX			
	End code: CR / CR + LF / none / ETX			
Data transmission order	Transmit from bit 0 in character units.			
Communication mode	General-purpose communication, Computer link and MODBUS-RTU			

Note: SD, RD and SG terminals are isolated from internal circuits.

# Dedicated power supply output port specifications for GT series programmable display

Output terminal (Note 1)	Connecting programmable display model			
5 V	For 5 V DC type <b>GT</b> series Programmable Display			
24 V (Note 2)	For 24 V DC type <b>GT</b> series Programmable Display			

Notes: 1) 5 V and 24 V DC types are not usable at the same time.

2) Use 21.6 to 26.4 V DC to power the CPU unit.

Please confirm the "GT Series Manual" for grounding of the GT series programmable display.

The AFP7CPS21 is not provided with this port.

# LAN port communication specifications [except for AFP7CPS31(S) / AFP7CPS21]

Item	Specifications			
Communication interface	Ethernet 100BASE-TX / 10BASE-T			
Baud rate	100 Mbps, 10 Mbps auto negotiation function			
Total cable length	100 m 328 ft (500 m 1,640 ft when a repeater is used)			
Number of nodes	Max. 254 units			
Number of simultaneous connections	Max. 220 connections (user connection: 216, system connection: 4)			
Communication protocol (Communication layer)	TCP/IP, UDP			
DNS	Supports name servers			
DHCP / DHCPV6	Automatic IP address acquisition			
FTP server / Client (SSL compatible)	Server function: file transfer, number of user: 3 Client function: data and file transfer			
HTTP server / Client (SSL compatible)	Server function: system web, customer web (8 MB), number of concurrent session: 16 Client function: data transfer			
SMTP client (SSL compatible)	Client function: mail transfer			
SNTP	Time adjustment function			
General-purpose communication	16 kB / 1 connection (user connection: 1 to 16)			
Dedicated communication	Slave communication (MEWTOCOL-COM, MEWTOCOL7-COM, MEWTOCOL-DAT, MODBUS-TCP, MC protocol (Note)) Master communication (MEWTOCOL-COM, MEWTOCOL-DAT, MODBUS-TCP, MC protocol (Note))			

Note: MC protocol is a short form denoting MELSEC communication protocol; MELSEC is a registered trademark of Mitsubishi Electric Corporation.

QnA compatible 3E frame, only binary (bulk writing and bulk reading) use is available.

### Web server specifications

Item	Specifications
Compatible CPU unit	Ver. 3.30 or later CPU unit with built-in Ethernet function
Web server	Number of simultaneous accesses: 16 sessions System Web: system monitor function Custom Web: 13.83 MB max. content capacity
Control Web Creator compatible OS	Windows® 7 or higher
Web server accessible browsers	Windows® Google Chrome Mozilla Firefox Opera Internet Explorer OS X Safari Google Chrome Mozilla Firefox iOS Safari Google Chrome Android Google Chrome

Notes: 1) Windows and Internet Explorer are registered trademarks or trademarks of Microsoft Corporation in the United States and other countries.

Google Chrome and Android are registered trademarks of Google Inc.

Safari and OS X are trademarks or registered trademarks of Apple Inc. in the United States.

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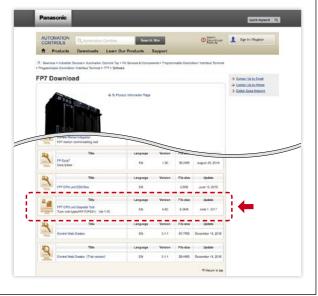
Firefox is a registered trademark of Mozilla Foundation in the United States and other countries.

Opera is a trademark or registered trademark of Opera Software ASA

Please use the latest OS and browser versions.
 Latest browser versions may not work with older models.

### Firmware can be updated to latest version!

Update tool for latest firmware version is available on our website. Web server function can be added to CPU units listed above with built-in Ethernet function.



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UV CURING SYSTEMS

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Program
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FPΣ FP-X FP2SH

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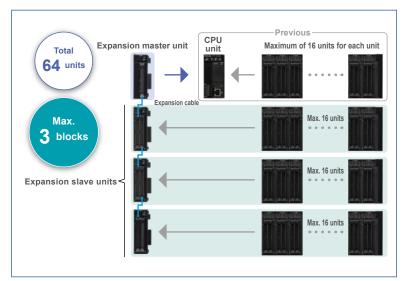
FP-e

### **EXPANSION UNITS**



### Connect a maximum of 3 blocks and a total of 64 units

Three blocks can be expanded on one CPU unit.



### **SPECIFICATIONS**

	Product name	Expansion master unit	Expansion slave unit		
Item	Part No.	AFP7EXPM	AFP7EXPS		
CE marking directive compliance		EMC Directive,	RoHS Directive		
Number of	Block	Max. 3 blocks	(total 4 blocks)		
expansion	Unit	Max. 48 units (total 64 units)			
Transmission	Distance between blocks	Length of expansion cable (0.5 m 1.640 ft, 1	m 3.281 ft, 3 m 9.843 ft and 10 m 32.808 ft)		
distance	Total extension	Max. 30 m 98.425 ft (Expansion cable × 3 expansions) (Note 1)			
Current consum	ption (Note 2)	120 mA or less	100 mA or less		
Max. allowable current		<del></del>	3.0 A (at 24 V DC power supply terminal)		
Expansion bus connector		MIL 40 pins	MIL 40 pins × 2		
Accessories			Power supply cable (Part No.: <b>AFPG805</b> ) End unit (Part No.: <b>AFP7END</b> )		

Notes: 1) Can support a maximum of 100 m 328 ft length between blocks. Please inquire with us for details.

- 2) Differs depending on power supply voltage and number of expansion units.
- 3) You cannot use the expansion units with the **AFP7CPS21** CPU unit.

### ADD-ON CASSETTES (COMMUNICATION CASSETTES)



### For communication with programmable displays or PCs and for data exchange between PLCs

### Serial communication and Ethernet communication can be added to the CPU unit

6 types are available including cassettes that support any combination of RS-232C, RS-422, RS-485 and Ethernet.

### [Configuration example]



\* Ethernet function (including FTP server / client function, HTTP client function, Web server function and E-mail sending function) cannot be used in the AFP7CCET1.

### **Protocol supports MODBUS-RTU**

Communication can easily be accomplished using comfortable communication instructions.

Note: The AFP7CCET1 supports MODBUS-RTU as well, and does not support MODBUS-TCP.

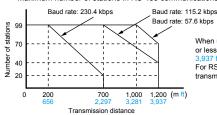
### **SPECIFICATIONS**

Item	AFP7CCS1 AFP7CCS2 (Note 7) AFP7CCM1 (Note 6) AFP7CCM2 (Note 6) AFP7CCS1M1						
CE marking directive compliance			EMC Directive, RoHS Directive				
Interface	RS-232C 1 channel   RS-232C 2 channels   RS-422 or RS-485 1 channel   RS-422 or RS-485 2 channels   RS-232C 1 channel and RS-485 1 channel						
Transmission distance	Max. 15 m 49	.213 ft (Note 2)	Max. 1,200 m 3,937 ft at RS-485 mode (Note 3, 4) Max. 400 m 1,312 ft at RS-422 mode (Note 3, 4)	Max. 15 m 49.213 ft (RS-232C) (Note 2)	Max. 1,200 m 3,937 ft (RS-485) (Note 3, 4)		
Transmission speed		300, 600, 1,200, 2,4	00, 4,800, 9,600, 19,200, 38,400, 57,600, 11	5,200, 230,400 bits/	sec.		
Communication method	Half-duplex						
Synchronous method	Start-stop synchronization						
	Stop bit: 1 bit / 2 bits						
	Parity: none / odd / even						
Transmission format	Data length: 7 bits / 8 bits						
	Start code: with STX / without STX						
	End code: CR / CR + LF / none / ETX						
Data transmission order	Transmit from bit 0 in character units.						
			For program controlled communication: max. 99 (Note 8)		For program controlled communication: max. 99		
Max. number of stations			For computer link: max. 99 (Note 8)		For computer link: max. 99		
(Note 2, 3, 4)			For PLC link: max. 16 (Note 8)		For PLC link: max. 16		
			For MODBUS-RTU: max. 99 (Note 8)		For MODBUS-RTU: max. 99		

Notes: 1) When connecting a commercially available device that has an RS-485 / RS-422 interface, please confirm operation using the actual device.

In some cases, the number of station units, transmission distance and communication speed vary depending on the connected device.

Maximum number of stations in RS-485 communications



When using a transmission speed of 38.4 kbits/sec. or less, you can set up a maximum of 1,200 m 3,937 ft and 99 units.
For RS-422 setting, you can set up a maximum

transmission distance of 400 m 1.312 ft.

ote 8) For MODBUS-RTU: max. 99

2) Cable length should be no longer than 3 m 9,843 ft if communicating at a rate of 38.4 kbits/sec. or higher. If you are using RS-232C wiring, shielded cable should be used to improve noise immunity.

3) For RS-485 setting, the values for transmission distance, transmission speed and number of connected units should be within the values noted in the left graph.

4) If mixed C-NET adapters are used, up to 32 units can be connected, but transmission speed will be limited to a maximum of 19.2 kbits/sec..

5) The converter SI-35 manufactured by LINE EYE Co., Ltd. is recommendable for the RS-485 at the computer side. When you use the SI-35, please adjust time after FP7 series PLC receives a command until it returns a response by a program.

6) RS-422 or RS-485 can be selected using the DIP switch built into the communication cassette.

7) Using the DIP switch built into the communication cassette allows the interface to be used as RS-232C 5-wire system × 1 channel.

Transmission dis	5,51 0,501
Transmission dis	sance
Item	AFP7CCET1
CE marking directive compliance	EMC Directive, RoHS Directive
Interface	Ethernet 100BASE-TX / 10BASE-TX
Communication speed	100 Mbps, 10 Mbps Auto negotiation function
Total cable length	100 m 328 ft (500 m 1,640 ft when a repeater is used)
Number of nodes	Max. 254 units
Number of simultaneous connections	Max. 4 connections (User connection: 3, System connection: 1)
Communication protocol (Communication layer)	TCP / IP, UDP
DHCP	Automatic IP address acquisition
General-purpose communication	4 kB / 1 connection
Dedicated communication	Slave communication (MEWTOCOL-COM, MEWTOCOL7-COM, MEWTOCOL-DAT)
Dedicated communication	Master communication (MEWTOCOL-COM, MEWTOCOL7-COM, MEWTOCOL-DAT)

Notes: 1) Please connect the Ethernet cable with the power turned off.
2) You cannot use this cassette "AFP7CCET1" with the serial communication unit.
3) Ethernet function (including FTP server / client function, HTTP client function, Web server function and E-mail sending function) cannot be used.

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FP-X FP2SH

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### ADD-ON CASSETTES (FUNCTION CASSETTES)



### Add Analog I/O, temperature input function

### Analog I/O and temperature input functions can be added to the CPU unit

Low cost expansion of the CPU unit with an analog function is easy and installation space can be reduced.



### Analog cassette

- Analog input (2 channels)
- · Analog input and output (input: 2 channels, output: 1 channel)
- Thermocouple (2 channels)

### Low cost addition of functions

Reduced cost and space are realized compared to the analog input and output unit.

### **SPECIFICATIONS**

### Analog input cassette / Analog input and output cassette

### Input specifications (AFP7FCAD2 / AFP7FCA21)

Item		AFP7FCAD2 / AFP7FCA21		
CE marking directive of	compliance	EMC Directive, RoHS Directive		
Number of input poi	nts	2 channels (non-insulated between channels)		
Input range	Voltage	0 to 10 V / 0 to 5 V *Switch setting (individual settings possible)		
	Current	0 to 20 mA		
Digital conversion value		K0 to K4000		
Resolution		1/4000 (12 bits)		
Conversion speed		1 ms/channel		
Overall precision		±1 % F.S. or less (0 to +55 °C +32 to +131 °F)		
Input	Voltage	1 ΜΩ		
impedance	Current	250 Ω		
Absolute maximum	Voltage	−0.5 V, +15 V		
input	Current	30 mA		
Insulation method		Between analog input terminal and internal digital circuit: transformer insulation, isolation IC insulation     Between analog input terminal and analog output terminal: transformer insulation, isolation IC insulation		
Connection method		Connector type terminal block		

Note: Input specifications of the analog I/O cassette and analog input cassette are the same.

### Thermocouple cassette

### Specifications (AFP7FCTC2)

	Item	AFP7FCTC2	
CE marking directive compliance		EMC Directive, RoHS Directive	
Number of	of input points	2 channels (insulated between channels)	
Input range	K type thermocouple	−50.0 to 500.0 °C −58.0 to 932.0 °F	
(Note)	J type thermocouple	−50.0 to 500.0 °C −58.0 to 932.0 °F	
	Normal time	K-500 to K5000	
Digital	When range over	K-501, K5001 or K8000	
conversion value	When the thermocouple broken	K8000	
	When data preparation	K8001	
Resolution		0.2 °C (Display is 0.1 °C with the software averaging process.)	
Sampling	cycle	100 ms / 2 channels	
Overall precision		±0.5 % F.S. or less and cold contact accuracy	
Input impedance		344 kΩ	
Insulation method		Between thermocouple input terminal and internal digital circuit: transformer insulation, isolation IC insulation     Between thermocouples: transformer insulation, isolation IC insulation	
Connection method		Connector type terminal block	

Note: Thermocouple setting can be switched with the switch on the front of the cassette.

### Analog input and output cassette

### Output specifications (AFP7FCA21)

Item		AFP7FCA21	
CE marking directive of	compliance	EMC Directive, RoHS Directive	
Number of output po	oints	1 channel	
Output range	Voltage	0 to 10 V / 0 to 5 V *Switch setting	
Output range	Current	0 to 20 mA	
Digital conversion v	alue	K0 to K4000	
Resolution		1/4000 (12 bits)	
Conversion speed		1 ms/channel	
Overall precision		±1 % F.S. or less (0 to +55 °C +32 to +131 °F)	
Output impedance		0.5 Ω (voltage output)	
Max. output current		10 mA (voltage output)	
Absolute output load resistance		600 Ω or less (current output)	
Insulation method		Between analog input terminal and internal digital circuit: transformer insulation, isolation IC insulation     Between analog input terminal and analog output terminal: transformer insulation, isolation IC insulation	
Connection method		Connector type terminal block	

Note: There is no analog output functionality in the analog input cassette.

### **DIGITAL INPUT AND OUTPUT UNITS**



Note: Photograph shows typical models for each shape.

### I/O points can be added as necessary

### Input/output mixed units are available

The necessary I/O points can be efficiently obtained, resulting in a compact PLC at reduced cost.

### The 64 points transistor output unit is designed for 300 mA current capacity

The 64 points transistor output unit is equipped with 8 contact points with 300 mA current capacity. Large indicator lamps, magnetic contacts, etc. can be driven directly.



### The noise countermeasure is possible by an adjustment of the input time constants

Response time can be selected from 0.1 ms, 0.5 ms, 1 ms, 5 ms, 10 ms, 20 ms or 70 ms, depending on the output equipment to be used.



### SPECIFICATIONS

### Input specifications

Item			DC input units	I/O mixed unit (input side)				
		16 points type	32 points type 64 points type		DC input / sink type DC input / source typ			
Insulation method			Photocoupler					
Rated input voltage		12 to 24 V DC	24 V	DC DC	24 V DC			
Rated input current		6 mA approx. (at 24 V)	2.7 mA		2.7 mA	3.4 mA		
Impedance		3.6 kΩ	8.2 kΩ		8.2 kΩ	7.5 kΩ		
Min. ON voltage / Min. ON current		9.6 V / 2 mA	19.2 V /	2.5 mA	19.2 V / 2.5 mA			
Max. OFF voltage	Max. OFF current	2.5 V / 1 mA	5 V / 1.5 mA		5 V / 1.5 mA			
Response time	OFF→ON	0.1 ms or less (Note 1)	0.2 ms or less (Note 1)		0.2 ms or less (Note 1)			
Response time	ON→OFF	0.2 ms or less (Note 1)	0.2 ms or less (Note 1)		0.2 ms or less (Note 1)			
Input points per common		8 points/common	32 points/common		32 points/common			
Connection method		Terminal block (M3 terminal screws)	Connector Connector (MIL-compliant 40 pins) (MIL-compliant 40 pins, two use)		compliant 40 pins)			

Notes: 1) Changeable by settable input time constant

2) CE marking directive compliance; EMC Directive, RoHS Directive

### Output specifications

Output spe	ecifications						
Item		Relay output unit	Transistor output units				I/O mixed unit (output side)
		16 points type	16 points (NPN)	32 points (NPN)	64 points (NPN)	16 points (PNP)	32 points (NPN)
Insulation method		Relay			Photocoupler		
Nominal switching capacity		2 A 250 V AC / 2 A 30 V DC					
Min. load		1 mA 100 mV DC (resistive load)					
Output type					Open collector		
Rated load vo	oltage				5 to 24 V DC		
Operating load	d voltage range				4.75 to 26.4 V DC		
current 0.1	) to Y7)		1 A	0.3 A (26.4 to 20.4 V DC) 30 mA (4.75 V DC)	0.3 A (20.4 to 26.4 V DC) 30 mA (4.75 V DC) 0.1 A (20.4 to 26.4 V DC) 15 mA (4.75 V DC)	1 A	0.3 A (20.4 to 26.4 V DC) 30 mA (4.75 V DC) 0.1 A (20.4 to 26.4 V DC) 15 mA (4.75 V DC)
Common rest		5 A	5 A	3.2 A/c	ommon	5 A	3.2 A/common
Max. surge ci	urrent		3 A	3 A 0.6 A		3 A	0.6 A
OFF state lea	kage current		1 μA or less			1 μΑ (	or less
ON state volta	age drop		0.5 V or less		0.5 V or less		
Response	OFF→ON	10 ms approx.	0.05 ms or less (at load current 0.5 mA or more)	0.1 ms or less (at load current 1 mA or more)		0.05 ms or less (at load current 0.5 mA or more)	current 2 mA or more)
time	ON→OFF	8 ms approx.	0.3 ms or less (at load current 0.5 mA or more)	0.3 ms or less (at load current 1 mA or more)	0.3 ms or less (at load current 1 mA or more)	0.3 ms or less (at load current 0.5 mA or more)	0.3 ms or less (at load current 2 mA or more)
Life time	Mechanical life	2 × 10 <sup>7</sup> operations or more					
Life tillle	Electrical life	1 × 10 <sup>5</sup> operations or more		<del></del>			
External power	Voltage			4.75 to 26.4 V DC		4.75 to 2	6.4 V DC
supply	Current (at 24 V)		70 mA	110 mA	70 mA/common	70 mA	70 mA
Surge absorber		Snubber circuit (leakage current: 0.2 mA or less)		Zener diode		Zener diode	
Short circuit protection						_	
Output points	per common	16 points/common	16 points/common	32 points	common /	16 points/common	32 points/common
External connection method		Terminal block	Terminal block	Connector	Connector	Terminal block	Connector

(M3 terminal screws) (M3 terminal screws) (MIL-compliant 40 pins) (MIL-compliant 40 pins, two use) (M3 terminal screws) (MIL-compliant 40 pins)

Note: CE marking directive compliance; EMC Directive, RoHS Directive (Only AFP7Y16R complies with Low Voltage Directive)

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> > FP-e

### **SPECIFICATIONS**

### **Output specifications**

Item		Transistor output units I/O mixed unit (output side)					
		Source type (PNP open collector)					
		32 points type 64 points type 32 points type					
1							
Insulation method			Photocoupler				
Output	type		Open collector				
Rated load voltage			5 to 24 V DC				
Load voltage allowable range		4.75 to 26.4 V DC					
Max. load	0.3 A (Y0 to Y7)	0.3 A	0.3 A (20.4 to 26.4 V DC) 30 mA (4.75 V DC)				
current	0.1 A (other than that above)	(26.4 to 20.4 V DC) 30 mA (4.75 V DC)	0.1 A (20.4 to 26.4 V DC) 15 mA (4.75 V DC)				
Common restriction		3.2 A/common					
Max. surge current		0.6 A					
OFF state leakage current		1 μA or less					

		Transistor output units 1/0 mixed unit (output side)				
	Item	Source to	ype (PNP open	collector)		
		32 points type 64 points type 32 points type				
ON state ma	aximum voltage drop		0.5 V or less			
Repose	OFF→ON	0.1 ms or less	s (at load current 2	2 mA or more)		
time	ON→OFF	0.5 ms or less (at load current 2 mA or more)				
External	Voltage	4.75 to 26.4 V DC				
power	Current	130 mA	90 mA/common	90 mA		
supply	(at 24 V)	130 IIIA 90 IIIA/COIIIIIOII		90 MA		
Surge a	bsorber	Zener diode				
Short cire	cuit protection					
Output po	ints per common	32 points/common				
Operating mode		32 points LED display 32 points LED display				
indicato	r	(lights when ON) (lights when ON, selectable by switch)				
External	I connection	Connector	Connector (MIL-compliant	Connector (MIL-compliant		
method		(MIL-compliant 40 pins)	40 pins, two use)	40 pins, one use)		

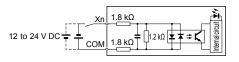
Note: CE marking directive compliance; EMC Directive, RoHS Directive

### I/O CIRCUIT DIAGRAMS

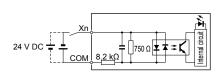
### DC input unit

### Input circuit diagrams

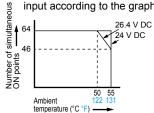
[16 points]



[32 points / 64 points]

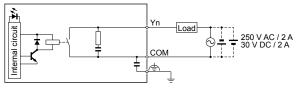


■Limitations on simultaneous ON points [64 points] Reduce simultaneous ON points of input according to the graph below.

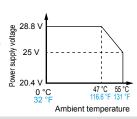


### Relay output unit

### **Output circuit diagram**



■Limitations on power supply voltage Reduce power supply voltage according to the right graph by the ambient temperature.

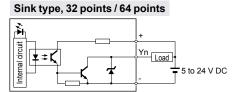


### Transistor output unit

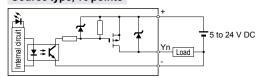
### **Output circuit diagram**

### Sink type, 16 points

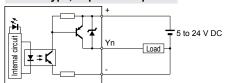
Internal circuit Yn Load |**≠** ≠ **K** 5 to 24 V DC



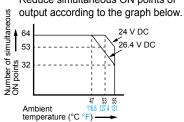
### Source type, 16 points



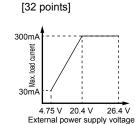
### Source type, 32 points / 64 points

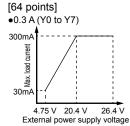


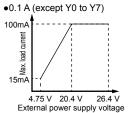
■Limitations on simultaneous ON points [64 points] Reduce simultaneous ON points of



Reduce load current according to the right graph by the external power supply voltage.





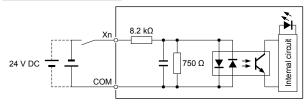


### I/O CIRCUIT DIAGRAMS

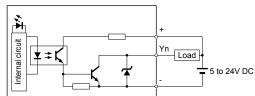
### I/O mixed unit

### I/O circuit diagram

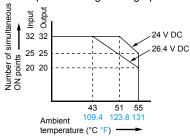
### Input circuit, sink type



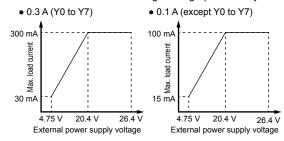
### Output circuit, sink type



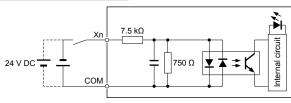
Limitations on simultaneous ON points (common to input and output) Reduce simultaneous ON points of input and output according to the graph below.



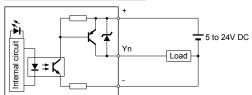
Reduce load current according to the graph below by the external power supply voltage.



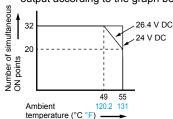
### Input circuit, source type



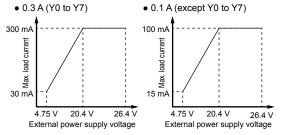
Output circuit, source type



Limitations on simultaneous ON points (common to input and output) Reduce simultaneous ON points of input and output according to the graph below.



Reduce load current according to the graph below by the external power supply voltage.



FIBER SENSORS

LASER SENSORS

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AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

> MACHINE VISION SYSTEMS

UV CURING

Applications

Software Program Transfer

Others

FP7

FP-X0 FP0R FPΣ

FP-X FP2SH

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Applications Software

FP7

Program Transfer Others

FP-X0 FP0R FPΣ FP-X

FP2SH FP-e

### **ANALOG INPUT AND OUTPUT UNITS**



### Channel insulation is switchable to support various devices

20 times faster conversion than in previous model: 25 µs/channel High-speed sampling that doesn't depend on CPU unit scanning

Sampling and data collection in the analog unit!

Use the measurement applications because with the fixed cycle, analog signal can be held in the buffer.

### Dependent on scan of CPU unit

The scan gets delayed when the CPU unit slows down due to other processes and sampling becomes sporadic.



### Sampling in the analog unit

Accurate sampling possible with fixed cycle.



High-accuracy of ±0.05 % F.S. (at +25 °C +77 °F) can be achieved Noise-resistant with isolated channels

### **SPECIFICATIONS**

### Analog input specifications (AFP7AD4H / AFP7AD8)

Number of channels		P:	art No.	AFP7AD4H	AFP7AD8	
Input range (Resolution, Max. 16 bits)	Item	Nun	nber of			
Input range (Resolution, Max. 16 bits)	CE marking direc	tive con	npliance	EMC Directive, RoHS Directive		
Current	Input range / Resolution, \			0 to 10 V (resolution: 1/31,250) 0 to 5 V (resolution: 1/31,250) 1 to 5 V (resolution: 1/25,000) (Note 2)		
Conversion speed   Current   (at non-insulated channels)   25 μs/channel   25 μs/channel (at non-insulated channels)   25 μs/channel   25 μs/channel	(Wax. 10 bits)	Curre	ent			
Coverall accuracy				(at non-insulated channels) 5 ms/channel (at insulated channels)	(at non-insulated channels)	
Insulation method    Digital processing   Digital processing   Digital processing   Offset setting   Any value within ±30,000   Gain setting   Any value within ±30,000   Gain setting   Any value within ±30,000   Conversion execution   Conversion execution   Conversion execution   Conversion of upper and lower limit values   Possible to make settings on a channel-by-channel basis (hysteresis)   When less than 0.7 V / 2.8 mA (only when voltage input -2 to +30 mA current input	Overall accur	асу		(at +25 °C +77 °F) ±0.1 % F.S. or less	(at +25 °C +77 °F) ±0.3 % F.S. or less	
Insulation method    Between input terminals and internal circuit						
Insulation method   Iterminals and internal circuit   Between channels   Photocoupler and isolated DC / DC converter   PhotoMOS relay	Max. input range					
Number of times   Number of times   Number of times   Setting range: 2 to 60,000 times		Insulation terminals and		Photocoupler and isolated DC / DC converter		
Digital processing  Moving  Scale conversion setting  Gain setting  Any value within ±30,000  Input range change method  Conversion execution / non-execution channel setting  Max. and min. value holding  Comparison of upper and lower limit values  Moving  Max. Broken wire detection  Itimes setting range: 1 to 1,500 ms (at non-insulated channels)  Range setting: 2 to 2,000 times  Any value within ±30,000  Any value within ±30,000  Selectable per channel  Selectable per channel unit  Possible to make settings on a channel-by-channel basis (hysteresis)  When less than 0.7 V 1.2 8 mA (only when voltage input range 4 to 20 mA is set.)  When less than 2.8 mA (only when voltage input range 4 to 20 mA is set.)		Between channels		PhotoMo	OS relay	
Digital processing Moving Range setting: 2 to 2,000 times    Scale conversion setting   Moving Range setting: 2 to 2,000 times				Setting range: 2 to 60,000 times		
Scale conversion setting Offset setting Any value within ±30,000  Gain setting Any value within ±30,000  Gain setting Any value within ±3,000  Input range change method Selectable per channel Conversion execution / non-execution channel setting  Max. and min. value holding Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis Comparison of upper and lower limit values  When less than 0.7 V 1.2 8 mA (only when voltage input range 4 to 20 mA is set.)		1		1,500 ms (at non-insulated channels), 200 to 60,000	1,500 ms (at non-insulated	
setting  Offset setting  Any value within ±3,000  Gain setting  Any value within ±3,000  Input range change method  Conversion execution / non-execution channel setting  Max. and min. value holding  Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis  Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis (hysteresis)  When less than 0.7 V/2.8 mA (only when voltage input range 4 to 20 mA is set.)	processing		Moving	Range setting: 2	2 to 2,000 times	
Gain setting		setting		,		
Input range change method   Selectable per channel		Offset	setting			
Conversion execution / non-execution channel setting  Max. and min. value holding  Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis  Possible to make settings on a channel-by-channel basis (hysteresis)  When less than 0.7 V / 2.8 mA (only when voltage input range 4 to 20 mA is set.)  When less than 2.8 mA (only when voltage input range 4 to 20 mA is set.)						
non-execution channel setting  Max. and min. value holding  Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis  Possible to make settings on a channel-by-channel basis (hysteresis)  When less than 0.7 V/2.8 mA (only when voltage input range 1 to 5 V or current input range 4 to 20 mA is set.)  When less than 2.8 mA (only when current input range 4 to 20 mA is set.)	Input range change method			Selectable	per channel	
Comparison of upper and lower limit values  Possible to make settings on a channel-by-channel basis (hysteresis)  When less than 0.7 V/2.8 mA (only when voltage input range 4 to 20 mA is set.)  Channel basis (hysteresis)  When less than 2.8 mA (only when current input range 4 to 20 mA is set.)				·		
Channel basis (hysteresis)	Max. and min. value holding				ngs on a channel-by-	
Broken wire detection (only when voltage input range 1 to 5 V or current input range 4 to 20 mA is set.) When less than 2.8 mA (only when current input range 4 to 20 mA is set.)						
Buffer function 3 trigger types: Soft trigger, External trigger and Input level	Broken wire detection			(only when voltage input range 1 to 5 V or current input range 4		
	Buffer function			3 trigger types: Soft trigger, External trigger and Input level		

Notes: 1) Please note that the digital converted value corresponding to
about 2 V of analog input is stored in the input relay area (WX)
for channels which are not connected to input when setting the
voltage range with AFP7AD8.

2) The full scale (F.S.	) on the accuracy of an analog voltage input
	and that of an analog current input range from
4 to 20 mA are 0 to	5 V and 0 to 20 mA, respectively.

	_	Part No.	AFP7AD4H	AFP7AD8		
Item		Number of channels 4 channels		8 channels		
	Insulation	n method	Photod	Photocoupler		
	Rated inpo	ut voltage / ut current	24 V DC / 4.5 mA approx. (at 24 V DC)	24 V DC / 12 mA approx. (at 24 V DC)		
	Input imp	edance	5.1 kΩ approx.	2 kΩ approx.		
	Operating v	oltage range	21.6 to 26.4 V DC			
Trigger input section	Min. ON voltage / Min. ON current		19.2 V / 3.5 mA			
	Max. OFF voltage / Max. OFF current		5 V / 1.5 mA			
	Response	OFF→ON	0.2 ms or less	0.1 ms or less		
	time	ON→OFF	0.2 ms or less	0.1 ms or less		
	Input points	per common	2 points/common	1 point/common		
Connection method		Terminal block (M3 terminal screw)				

### Analog output specifications (AFP7DA4H)

CE marking directive compliance         EMC Directive, RoHS Directive           Number of output channels         4 channels           Output range (Resolution, Max. 16 bits)         Voltage           Current         0 to 20 mA (resolution: 1/31,250) 4 to 20 mA (resolution: 1/25,000)           Conversion speed         Voltage / current           25 μs/channel           ± 0.1 % F.S. or less (at +25 °C +77 °F) + 0.3 % F.S. or less (at 0 to +55 °C +32 to +131 °F)
Output range (Resolution, (Max. 16 bits)  Current  Conversion speed Voltage / Current  Overall accuracy  -10 to +10 V (resolution: 1/62,500) 0 to 10 V (resolution: 1/31,250) 0 to 5 V (resolution: 1/31,250) 1 to 5 V (resolution: 1/25,000) 1 to 5 V (resolution: 1/25,000) 2 to 20 mA (resolution: 1/31,250) 4 to 20 mA (resolution: 1/25,000) 2 μs/channel  ± 0.1 % F.S. or less (at +25 °C +77 °F) ± 0.3 % F.S. or less (at 0 to +55 °C
Output range / Resolution, (Max. 16 bits)         Voltage         0 to 10 V (resolution: 1/31,250) 0 to 5 V (resolution: 1/31,250) 1 to 5 V (resolution: 1/31,250) 1 to 5 V (resolution: 1/25,000)           Current         0 to 20 mA (resolution: 1/31,250) 4 to 20 mA (resolution: 1/25,000)           Conversion speed         Voltage / current         25 μs/channel           Φoverall accuracy         ± 0.1 % F.S. or less (at +25 °C +77 °F) ± 0.3 % F.S. or less (at 0 to +55 °C
Current   U to 20 mA (resolution: 1/31,250)
± 0.1 % F.S. or less (at +25 °C +77 °F)  Overall accuracy ± 0.3 % F.S. or less (at 0 to +55 °C
Overall accuracy ± 0.3 % F.S. or less (at 0 to +55 °C
02 (0 101 1)
Output impedance (voltage output) $0.5 \Omega$ or less
Max. output current (voltage output) 10 mA
Permissible output load resistance (Current output) 500 Ω or less
Insulation method Between the input terminals Photocoupler and isolated DC / DC converter
Between channels Not insulated
Scale conversion setting  Any value within ±30,000
Offset and Offset setting Any value within ±3,000
gain function Gain setting Any value within 9,000 to 11,000
Output range change method Selectable per channel
Conversion execution / non-execution channel setting Selectable per channel unit
Upper and lower output limit clip Possible to make settings on a channel-by-channel basis
Analog output holding (in PROG mode) Present value / any value / not holding
Connection method Terminal block (M3 terminal screws)

### **TEMPERATURE INPUT UNITS**



### High-speed, high-accuracy and multi-channel input

# Easy to perform high-accuracy measurement

Equipped with a variety of functions required for temperature measurement Easy to obtain measurement results

Capable of high-speed and high-accuracy temperature input

Averaging processing	Number of times, time, moving
Insulation	Channels are insulated from one another and from the internal circuit.
Simple setting	Initial settings can be completed on the configuration screen.

	High-speed conversion	High-accuracy
Thermocouple multiple analog input unit	5 ms/channel (high-speed mode) 25 ms/channel (normal mode)	±0.1 % F.S. (at +25 °C +77 °F) ±0.3 % F.S.
Resistance temperature	25 ms/channel (normal mode)	(at 0 to +55 °C +32 to +131 °F)

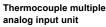
### **Multi-channel input**

One unit can control the input of up to 8 channels.

With so many channels, the unit eliminates the need to purchase additional units, reducing required space and costs.

The thermocouple multiple analog input unit can also control voltage and current inputs.







Resistance temperature detector input unit

### **SPECIFICATIONS**

	Product name	Thermocouple multiple analog input unit			
Item \	Part No.	AFP7TC8			
CE marking directive compliance		EMC Directive, RoHS Directive			
Number of c	hannels	8 channels			
		K1: -100.0 to +600.0 °C / K2: -200.0 to +1000.0 °C			
		J1: -100.0 to +400.0 °C / J2: -200.0 to +750.0 °C			
	Thermocouple	T: -270.0 to +400.0 °C / N: -270.0 to +1300.0 °C			
	(resolution: 0.1 °C)	R: 0.0 to +1760.0 °C / S: 0.0 to +1760.0 °C			
		B: 0.0 to +1820.0 °C / E: -270.0 to +1000.0 °C			
Innut rongo		PLII: 0.0 to +1390.0 °C / WRe5-26: 0.0 to +2315.0 °C			
Input range (resolution)		-10 to +10 V DC (resolution: 1/62,500) 0 to 5 V DC (resolution: 1/31,250)			
(resolution)	Voltage	1 to 5 V DC (resolution: 1/25,000) (Note 1)			
	vollage	-100 to +100 mV DC (resolution: 1/62,500)			
		Resolution: max. 16 bits			
		0 to 20 mA (resolution: 1/31,250)			
	Current	4 to 20 mA (resolution: 1/25,000) (Note 1)			
		Resolution: max. 16 bits			
		5 ms/channel + 5 ms (Note 2)			
Conversion s	eneed	25 ms/channel + 25 ms			
CONVENDION	pood	Add the drift compensation measuring time to the number of measuring channels.			
		9			
Overall accu	racy	±0.1 % F.S. or less (at +25 °C +77 °F) ±0.3 % F.S. or less (at 0 to +55 °C +32 to +131 °F)			
Deference cente	ct compensation accuracy	±1.0 °C (with thermocouple input)			
	Voltage / current	1 ΜΩ / 250 Ω			
Iliput Illipedance	Between input terminals	Photocoupler and			
Insulation	and internal circuit	isolated DC/DC converter			
method	Between channels	PhotoMOS relay			
Conversion 6		*			
	n channel setting	Selectable per channel unit			
	change method	Selectable per channel			
	Averaging	Number of times, time, moving			
Digital	Scale conversion setting	Any value within ±30,000 (Voltage and current range only)			
processing	Offset setting	Any value within ±3,000			
	Gain setting	±10 %			
Comparison	of upper and lower	Possible to make settings on a channel-			
limit values		by-channel basis.			
Max and mir	n. value holding	Possible to make settings on a channel-			
		by-channel basis.			
Broken wire detection		Available			
Connection r	method	Connector type terminal block			

Notes: 1) The full scale (F.S.) ranges of accuracy are 1 to 5 V DC for voltage and 0 to 20 mA for current input, respectively.

2) The AC noise removal is disabled.

	Product name	Resistance temperature detector input unit			
Item	Part No.	AFP7RTD8			
CE marking	directive compliance	EMC Directive, RoHS Directive			
Number of o	channels	8 channels			
Input range (resolution)	Resistance temperature detector (resolution: 0.1 °C)	Pt100 (1): -100.0 to +200.0 °C Pt100 (2): -200.0 to +650.0 °C JPt100(1): -100.0 to +200.0 °C JPt100(2): -200.0 to +650.0 °C Pt1000: -100.0 to +100.0 °C			
Conversion	speed	25 ms/channel + 25 ms Add the drift compensation measuring time to the number of measuring channels.			
Overall accu		±0.1 % F.S. or less (at +25 °C +77 °F) ±0.3 % F.S. or less (at 0 to +55 °C +32 to +131 °F)			
Allowable sig	gnal source resistance	R.T.D. input: 30 Ω (three wires balanced)			
Insulation method	Between input terminals and internal circuit	Photocoupler and isolated DC/DC converter			
metriou	Between channels	PhotoMOS relay			
Conversion non-execution	execution / on channel setting	Selectable per channel unit			
Input range	change method	Selectable per channel			
Digital	Averaging	Number of times, time, moving			
processing	Offset setting	Any value within ±3,000			
processing	Gain setting	±10 %			
Comparison limit values	of upper and lower	Possible to make settings on a channel-by-channel basis.			
Max. and m	in. value holding	Possible to make settings on a channel- by-channel basis.			
Broken wire	detection	Available			
Connection	method	Connector type terminal block			

FIBER SENSORS

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AREA

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PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

> SIMPLE WIRE-SAVING UNITS

WIRE-SAVING

MEASURE-MENT SENSORS

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FP-X0 FP0R

FP-X

FP2SH

LASER SENSORS PHOTO-ELECTRIC SENSORS

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CURING

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Program Transfer Others

> FP-X0 FP0R

FP-X FP2SH

FP-e

### **MULTI INPUT AND OUTPUT UNIT**



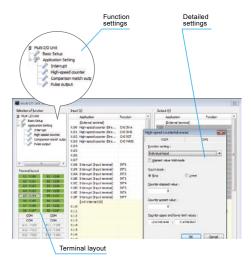
### Multifunctional control achieved in one unit!

### Accomplish highly functional control at the best price.

Highly functional control is possible using with best value model CPU unit AFP7CPS21.

### **Settings executed with FPWIN GR7**

Unit settings easily performed using configuration screen.



# Fixed cutting of material controlled by one unit.

# Motor control (PWM) (Positioning\*) \*Positioning type only

### **SPECIFICATIONS**

### Function specifications (AFP7MXY32DWD / AFP7MXY32DWDH)

Item			AFP7MXY32DWD	AFP7MXY32DWDH		
CE r	narking direc	tive compliance	EMC Directive, RoHS Directive			
Ħ	Number of o	ccupied I/O points	Input / Output: 64 points each (4 words)	Input / Output: 96 points each (6 words)		
outp	Number of e	xternal I/O points	Input: 16 points,	Output: 16 points		
Basic input and output	Input time	constant setting	None, 0.5 µs, 1 µs, 2 µs, 4 µs, 8 µs, 16 µs, 32 µs, 64 µs, 96 µs, 128 µs, 256 µs, 2 ms, 4 ms or 8 ms Setting possible in 2-point units (Note 1)			
Basic	Output polarity setting		(push pull output), and d Setting possible in 4-po	int units		
Interrupt	Number	of points	8 points/unit (Max. of 8 <b>FP7</b> system when setting			
terr	Mode		Non-interrupt unit, interrupt	unit (Set using DIP switches)		
드	Interrupt c	ondition setting	Terminal input, C	omparison match		
	Counter	type	Ring counter,	Linear counter		
	Input mo	de	Direction discrimination, in	dividual input, phase input		
	Number	of channels	4 channe	Is (Note 1)		
	Counting	grange	Signed 32-bit (-2,147,483,648 to +2,174,483,647) Setting possible of upper and lower limits			
Counter	Max. cou	ntable speed	24 V input voltage: 25	0 kHz (350 kHz with ase input) (Note 2)		
S	Min. inpu	t pulse width	0.5 µs			
	Compariso	n output setting	Max. 8 points Terminal input counter: 4 channels			
	Others		Transfer multiplication f Elapsed value offset / p Elapsed value hold fund lower count limits Input pulse frequency n Overflow / underflow de	reset function (× 1, × 2, × 4) reset function ction, setting of upper /		
	Number of	of channels	4 cha	innels		
	Output n	node	Direction discrimination, individual input, phase input, comparison match stop			
Ħ	Output	Pulse output function	2 terminals/channel (B11 to B18 terminals)			
<del>d</del>	terminals	PWM output function	1 terminal/channel (B11, B	13, B15 and B17 terminals)		
Pulse output	Output	Pulse output function	1 to 500 kHz (Note	3) (1 Hz increments)		
Puls	. '	PWM output function	1 to 100 kHz (Note	3) (1 Hz increments)		
	Duty	Pulse output function	50 % app	rox. (fixed)		
	PWM output function		0 to 100 % (Set in 0.1% increments)			
	Other functions		Pulse number measurement function (dedicated pulse counter 4 channels)			

Notes: 1) When using elapsed value hold function, number of channels will be limited. 2) With 50 % duty input pulse.

3) When push pull setting or output current is 0.1 A. Varies according to load.

### Positioning function specifications (AFP7MXY32DWDH)

Usage example

Position setting mode Position setting mode Output interface Output interface Transistor open collector output, Push-pull, Line driver (Note 1) Pulse output method Pulse + Sign, CW + CCW Max. output frequency Output pulse duty ratio Control unit Pulse Position setting range Pulse : 1 to 500,000 Hz Acceleration speed Acceleration time I to 10,000 ms (Settable by 1 ms) Deceleration method (Single axis) Control method (Single axis) Control method (Saxis linear interpolation) Dwell time Position setting range Pulse : 1 to 500,000 Hz Acceleration fire Promotol (E point control, C point control), CP control (P point control) (Speed control), CP control (P point control), Speed control (U point control), Composite speed or Long axis speed setting Dwell time Pulse Promotol (E point control, C point control), Composite speed or Long axis speed setting Dwell time Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 1 to 10,000 ms (Settable by 1 ms) Pulse: 1 to 500,000 Hz Acceleration fire 2 fire fire fire fire fire fire fire fire		Item	AFP7MXY32DWDH	
Output interface Pulse output method Pulse + Sign, CW + CCW  Max. output frequency Output pulse duty ratio Position setting range Speed command range Acceleration time Deceleration time Devel time Output method Position setting range Acceleration time Deceleration	Nun	nber of axes controlled	Max. 4 axes	
Position setting range		Position setting mode	Increment, Absolute	
Position setting range	ations	Output interface	Transistor open collector output, Push-pull, Line driver (Note 1)	
Position setting range	ecific	Pulse output method	Pulse + Sign, CW + CCW	
Position setting range	non sp	Max. output frequency	500 kHz	
Position setting range Speed command range Max. operation speed Acceleration / deceleration method Acceleration time Deceleration time To 10,000 ms (Settable by 1 ms) Deceleration method (Single axis) Control method (Single axis) Control method (2-axis linear interpolation) Dwell time Deceleration / deceleration method Acceleration / deceleration Dwell time Deceleration time To 10,000 ms (Settable by 1 ms) PTP control (E point control, C point control), CP control (P point control), as peed or Long axis speed setting Dwell time Deceleration / deceleration method Acceleration / deceleration method Linear acceleration / deceleration Acceleration / deceleration method Linear acceleration / deceleration Deceleration time To 10,000 ms (Settable by 1 ms) Deceleration ime To 10,000 ms (Settable by 1 ms) Deceleration fime To 10,000 ms (Settable by 1 ms) Deceleration fime To 10,000 ms (Settable by 1 ms) Deceleration ime To 10,000 ms (Settable by 1 ms) Deceleration ime To 10,000 ms (Settable by 1 ms) Deceleration ime To 10,000 ms (Settable by 1 ms) Deceleration time	Comu	Output pulse duty ratio	When using table setting mode: 50 % (fixed)	
Speed command range Max. operation speed  Acceleration / deceleration method Acceleration time 1 to 10,000 ms (Settable by 1 ms) Deceleration time 1 to 10,000 ms (Settable by 1 ms)  PTP control (E point control), C point control), CP control (P point control) axis linear interpolation) Dwell time  O to 32,767 ms (Settable by 1 ms)  Peded command range Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method Linear acceleration / deceleration  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration  Acceleration / deceleration  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration / deceleration  Acceleration / deceleration / deceleration  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration / deceleration / deceleration  Acceleration / deceleration / deceleration  Deceleration / deceleration / deceleration  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration / deceleration / deceleration  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration / deceleration method Deceleration stop  Pulse: 1 to 500,000 Hz  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration / deceleration method Deceleration stop  Pulse: 1 to 500,000 Hz  Acceleration / deceleration method Deceleration / deceleration / deceleration  Acceleration / deceleration method Deceleration stop  Pulse: 1 to 500,000 Hz  Acceleration / deceleration method Deceleration / deceleration method / deceleration / dece		Control unit	Pulse	
Max. operation speed   S00 kHz   Acceleration / deceleration method   Linear acceleration / deceleration   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Number of positioning tables   20 tables for each axis (Up to 2 tables can be executed consecutively.)   PTP control (E point control), C point control), CP control (P point (Single axis))   Control method (2-axis linear interpolation)   Dwell time   0 to 32,767 ms (Settable by 1 ms)   Speed command range   Pulse: 1 to 500,000Hz (Note 3)   Acceleration / deceleration method   Linear acceleration / deceleration   Acceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Pulse: 1 to 500,000 Hz   Acceleration / deceleration method   Linear acceleration / deceleration   Acceleration / deceleration method   Linear acceleration / deceleration   Acceleration / deceleration method   Linear acceleration / deceleration   Acceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration time   1 to 10,000 ms (Settable by 1 ms)   Deceleration stop   Performs deceleration stop in the deceleration time of a running operation for each axis.   Emergency stop   Stops in a deceleration time specified for the emergency stop for each axis.		Position setting range	-1,073,741,824 to +1,073,741,823 pulses	
Acceleration / deceleration method Deceleration time 1 to 10,000 ms (Settable by 1 ms) Deceleration time 1 to 10,000 ms (Settable by 1 ms) Number of positioning tables Control method (Single axis) Control method (2-axis linear interpolation) Dwell time Deceleration method Control method (2-axis linear interpolation) Dwell time  Performed Control method Dwell time  Speed command range Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000Hz (Note 3)  Acceleration ime 1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000 Hz  Acceleration / deceleration Acceleration ime 1 to 10,000 ms (Settable by 1 ms)  Deceleration ime 1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000 Hz  Acceleration / deceleration Acceleration ime 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration time 1 to 10,000 ms (Settable by 1 ms)		Speed command range	Pulse : 1 to 500,000 Hz	
Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Number of positioning tables  Control method (Single axis)  Control method (2-axis linear interpolation)  Dwell time  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000Hz (Note 3)  Epoint, P point, C point control), (Note 2) (Note 3)  Acceleration / deceleration  Acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration ime  1 to 10,000 ms (Settable by 1 ms)  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration ime  1 to 10,000 ms (Settable by 1 ms)  Deceleration ime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed co		Max. operation speed	500 kHz	
(Single axis) control), Speed control (J point control) (Note 2) (Note 3)  Control method (2-axis linear interpolation)  Dwell time  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration stop  Performs deceleration time deceleration itime of a running operation for each axis.  Stops in a deceleration time specified for the emergency stop for each axis.	2	Acceleration / deceleration method	Linear acceleration / deceleration	
(Single axis) control), Speed control (J point control) (Note 2) (Note 3)  Control method (2-axis linear interpolation)  Dwell time  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration stop  Performs deceleration time deceleration itime of a running operation for each axis.  Stops in a deceleration time specified for the emergency stop for each axis.	Son	Acceleration time	1 to 10,000 ms (Settable by 1 ms)	
(Single axis) control), Speed control (J point control) (Note 2) (Note 3)  Control method (2-axis linear interpolation)  Dwell time  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration stop  Performs deceleration time deceleration itime of a running operation for each axis.  Stops in a deceleration time specified for the emergency stop for each axis.	ē	Deceleration time	1 to 10,000 ms (Settable by 1 ms)	
(Single axis) control), Speed control (J point control) (Note 2) (Note 3)  Control method (2-axis linear interpolation)  Dwell time  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration stop  Performs deceleration time deceleration itime of a running operation for each axis.  Stops in a deceleration time specified for the emergency stop for each axis.	ositi			
Dwell time 0 to 32,767 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000Hz (Note 3)  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Speed command range Pulse: 1 to 500,000 Hz  Acceleration / deceleration method Linear acceleration / deceleration  Acceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Performs (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.	₾.	(Single axis) Control method	control), Speed control (J point control) (Note 2) (Note 3)  E point, P point, C point controls, Composite	
Acceleration / deceleration method  Linear acceleration / deceleration  Acceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration method  Linear acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop  Stops in a deceleration time specified for the emergency stop for each axis.				
Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  Deceleration stop  Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop  Stops in a deceleration time specified for the emergency stop for each axis.		Speed command range	Pulse: 1 to 500,000Hz (Note 3)	
Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  Deceleration stop  Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop  Stops in a deceleration time specified for the emergency stop for each axis.	eration	Acceleration / deceleration method	Linear acceleration / deceleration	
Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Speed command range  Pulse: 1 to 500,000 Hz  Acceleration / deceleration  Acceleration itime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  1 to 10,000 ms (Settable by 1 ms)  Deceleration time  Deceleration stop  Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop  Stops in a deceleration time specified for the emergency stop for each axis.	99	Acceleration time	1 to 10,000 ms (Settable by 1 ms)	
Acceleration / deceleration method Acceleration ime  1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 1 to 10,000 ms (Settable by 1 ms)  Deceleration time 2 DOG methods (3 types), Home position method, Data set method Deceleration stop 2 Deceleration stop 3 Deceleration stop 3 Deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop 3 Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop 3 Stops in a deceleration time specified for the limit input for each axis.	5	Deceleration time	1 to 10,000 ms (Settable by 1 ms)	
Return method DOG methods (3 types), Home position method, Data set method  Deceleration stop Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.	_	Speed command range	Pulse: 1 to 500,000 Hz	
Return method DOG methods (3 types), Home position method, Data set method  Deceleration stop Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.	Ĭ	Acceleration / deceleration method	Linear acceleration / deceleration	
Return method DOG methods (3 types), Home position method, Data set method  Deceleration stop Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.	ē	Acceleration time	1 to 10,000 ms (Settable by 1 ms)	
Return method DOG methods (3 types), Home position method, Data set method  Deceleration stop Performs deceleration stop in the deceleration time of a running operation for each axis.  Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.	P	Deceleration time	1 to 10,000 ms (Settable by 1 ms)	
Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.		Return method	DOG methods (3 types), Home position method, Data set method	
Emergency stop Stops in a deceleration time specified for the emergency stop for each axis.  Limit stop Stops in a deceleration time specified for the limit input for each axis.  System stop Stops all axes immediately.	E	Deceleration stop	Performs deceleration stop in the deceleration time of a running operation for each axis.	
Limit stop   Stops in a deceleration time specified for the limit input for each axis.	unctic	Emergency stop	Stops in a deceleration time specified for the emergency stop for each axis.	
System stop Stops all axes immediately.	stop fu	Limit stop	Stops in a deceleration time specified for the limit input for each axis.	
	<i>O</i>	System stop Stops all axes immediately.		

Notes: 1) The number of axes is reduced when setting Line driver.

- 2) The J point control is executable only for the two axes of CH0 and CH1.
- When performing the J point control or JOG operation, the speed can be changed after the startup.

### **HIGH-SPEED COUNTER UNITS**



### One of the fastest in industry added in lineup

### Industry-leading class speed of 16 Mpps (for differential input and 2-phase, 4-multiple)

Accurate, real-time surveillance of inverter and motor rotation speed variation.

### Supports 5 / 12 / 24 V DC and differential input.

Supports wide range of interface from 12 to 24 V DC, 5 V DC and differential input with one unit.

### Powerful application support

Input pulse string frequency (period) can be measured inside the unit with built in periodical pulse counter function. Built-in ring counter function can easily detect index table position. Line speed adjustment and work length measurement are available with built-in clock that allows accurate time measurement.

### Various functions can be used without a ladder program

Capture function of count value	Finite difference calculation of capture value	Interrupt using comparison match
Comparison match and band comparison	Measurement of frequency and number of revolution	Reset of Z number and preset
Reset and preset of external signal	Built-in clock selection	

### SPECIFICATIONS

Interrupt input function

		Туре	2 channels type	4 channels type		
Item		Part No.	AFP7HSC2T	AFP7HSC4T		
CE marking directive compliance			EMC Directive, RoHS Directive			
	Insulation method		Photocoupler			
	Rated input voltage		12 to 24 V DC / 3.5 to 5 V DC			
	Input impedance	24 V DC / 5 V DC	3.0 kΩ approx.	/ 390 Ω approx.		
	Usage voltage range	24 V DC / 5 V DC	10.8 to 26.4 V DC	/ 3.5 to 5.25 V DC		
Input	Min. ON voltage /	24 V DC	10 V D0	C / 4 mA		
	Min. ON current	5 V DC	3.0 V D	C / 4 mA		
	Min. OFF voltage /	24 V DC	2.0 V D	C / 2 mA		
	Min. OFF current	5 V DC	1.0 V DC	: / 0.5 mA		
	Input time constant setting		None, 0.1 μs, 0.2 μs, 0.5 μs, 1.0 μs, 2.0 μs and 10.0 μs			
	Number of counters		2 channels	4 channels		
	Counter type		Linear counter / Ring counter			
	Counting range		Signed 32-bit ( -2,147,483,648 to +2,147,483,647 )			
Count function	Max. input frequency		4 MHz / 8 MHz for individual input (phases A and B) (Duty ratio 50 ±10 %) 4 MHz / 8 MHz for direction discrimination input (Duty ratio 50 ±10 %) 4 MHz / 8 MHz /16 MHz for 2-phase input (Duty ratio 50 ±10 %, Phase shifting below 5 %)			
Count function	Input signal		Phases A, B and Z			
	External I/O		Control signal input: 4 points (2 points/ch) External output: 4 points (2 points/ch)	Control signal input: 8 points (2 points/ch External output: 8 points (2 points/ch)		
	Counter input type		Individual input: 1 multiple, 2-multiple Direction discrimination input: 1 multiple, 2-multiple 2-phase input: 1 multiple, 2-multiple, 4-multiple			
Measurement function	Frequency measurement function Measures the intervals between the variations of count values, and calculates the frequence					
Comparison function	Target value match function Depending on the count direction, sets or resets the output when the count direction is the count direction.			utput when the counter value reaches the target value.		
External output	Comparison result	output function	tion Outputs the result of comparison function.			
Capture function or ca			Acquires the current count value from the edges of input signals, and stores it in the capture 0 register or capture 1 register. The value of the specified capture register will be overwritten by a new value and the old value will be discarded every time a counter value is captured.			

Notes: 1) The interrupt input function can be used for 8 points per unit and for a maximum of 8 units (max. 64 points) in the whole system. However, the entire scan time slows down as more interrupt programs are used. Minimize the use of interrupt programs.

2) The priority order for interrupt inputs is as follows; In a unit, from the smallest interrupt bit. In the whole system, from the smallest unit number.

Available (2 points/ch, Max. 8 points/unit) (Note 1, 2)

LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

FA COMPONENTS

MACHINE VISION SYSTEMS

Applications

Software Program Transfer

Others

FP-X0

FP0R

FPΣ FP-X

FP2SH

LASER SENSORS

PHOTO-ELECTRIC SENSORS

AREA SENSORS

COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS PARTICULAR

SENSORS SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

HUMAN MACHINE INTERFACES

FA COMPONENTS MACHINE

VISION SYSTEMS

CURING SYSTEMS

Applications

Software Program Transfer Others

FP7

FP-X0 FP0R FPΣ FP-X

FP2SH

FP-e

### **POSITIONING UNITS**



### Combined multi-axle control can be achieved at reduced cost

### Equipped with electronic cam and electronic gear functions

Ladder program is capable of controlling electronic cams and gears. Virtual axes are supported and operable without connecting to external encoders.

### Organized wiring to servo amplifier

A servo ON output terminal is provided that allows simple and neat wiring to the servo amplifier. Also, wiring from the I/O unit is unnecessary, and a test run is possible by only a positioning soft tool.



### **Dedicated configuration tool**

Start positioning dedicated configuration tool using Control FPWIN GR7. Parameter and positioning operation settings can be made easily.

Test operation is also supported. Positioning operations can be checked even-while the CPU unit is in program mode.



### **SPECIFICATIONS**

Item			Specifications					
		щ	<del>;</del> 111		2 axes	s type	4 axes	s type
Part No.			AFP7PP02T	AFP7PP02L	AFP7PP04T	AFP7PP04L		
CE marking directive compliance					RoHS Dire			
Output type			Transistor		Transistor			
	x. operati				500 kpps		500 kpps	4 Mpps
Nu	mber of a	xes	controlle	ed	2 axes 4 axes			
Interpolation control		2 axes linear int 2 axes circular i		2 axes linear into 3 axes linear into 2 axes circular in 3 axes spiral into	erpolation, nterpolation and			
Ро	sition com	nma	nd units		inch (The minimum o	command unit can be	selected from 0.1 µm o selected from 0.0000 be selected from 0.1 d	1 inch or 0.0001 inch.)
Ро	sition con	nmand range		pulse: -1,073,741,823 to +1,073,741,823 pulse µm (0.1 µm): -107,374,182.3 to +1,073,741,82.3 µm µm (1 µm): -1,073,741,823 to +1,073,741,823 µm inch (0.0001 inch): -10,737,41823 to +107,374,1823 inch degree (0.1 degree): -107,374,182.3 to +107,374,182.3 deg degree (1 degree): -1,073,741,82.3 to +1,073,741,823 degr		im 41823 inch 1823 inch 74,182.3 degree		
Sp	eed comn	nan	d range		pulse: 1 to 32,767,000 pps µm: 1 to 32,767,000 µm/sec. inch: 0.001 to 32,767.000 inch/sec. degree: 0.001 to 32,767.000 rev/sec. *Specify an output speed that is below the maximum operating speed.			
			sition co ethod	mmand	Absolute (Absolute position designation), Increment (Relative position designation)			
			leration / decele		Linear acceleration / deceleration, S-curve acceleration / deceleration			
_		_	celeratio		0 to 10,000 ms (in increments of 1 ms)			
읉		Deceleration			0 to 10,000 ms (in increments of 1 ms)			
ers			per of positioning	tables per axis			, expansion ar	
Automatic operation	Position control	Indeper 2-axis interpolation 3-axis interpolation		ndent			, C point contro I control (J poin	
Jat	CONTROL	Ĕ	2-axis	Linear			ecify synthesis speed	
ton		5	interpolation				rols: center point	
Au		out	3-axis	Linear			ecify synthesis speed	
•			interpolation				rols: center point	
		-	artup tim		Standard area	: 3 ms or less,	expansion area	: 5 ms or less
		Other Dwell time			0 to 32,76	67 ms (in i	ncrements	of 1 ms)

Item			Specifications	
			2 axes type 4 axes type	
Pa	rt No.		AFP7PP02T AFP7PP02L AFP7PP04T AFP7PP04L	
		Acceleration /	Linear acceleration / deceleration,	
	JOG	deceleration method	S-curve acceleration / deceleration	
tion	operation	Acceleration / deceleration time	0 to 10,000 ms (in increments of 1 ms)	
pera		Acceleration / deceleration method	Linear acceleration / deceleration	
Manual operation	Home return	Acceleration / deceleration time	0 to 10,000 ms (in increments of 1 ms)	
Mar		Return methods	7 methods: DOG method (3 types), Limit method (2 types), Data set method, Z-phase method	
	Pulser operation	Speed command range	Operates in synchronization with pulser input	
- Lo	Deceleration stop	Deceleration time	Deceleration time of running operation	
Stop function	Emergency stop	Deceleration time	0 to 10,000 ms (in increments of 1 ms)	
₹	Limit stop	Deceleration time	0 to 10,000 ms (in increments of 1 ms)	
9	Error stop	Deceleration time	0 to 10,000 ms (in increments of 1 ms)	
<u>x</u>	System stop	Deceleration time	Immediate stop (0 ms), all axes stop	
5	Synchronous	Master axis	Existing axes, virtual axes or pulse input (1 to 4)	
호	basic setting	Slave axis	Max. 2 axes Max. 4 axes	
₹	Electronic gear function	Operation setting	Gear ratio setting	
<u>.</u> E		Operation method	Direct method, Acceleration / deceleration method	
iat	Electronic clutch function	Clutch ON trigger	Contact input	
obe		Clutch method	Direct method, Linear slip method	
Synchronous operation function	Electronic	Cam curve	Select from 20 types Multiple curves can be specified within a phase (0 to 100 %).	
Ę	cam function	Resolution	1,024, 2,048, 4,096, 8,192, 16,384, 32,768	
	cam function	Number of cam patterns	4 to 16 (Depends on resolution)	
ations	Output mode		1 pulse output (pulse + direction), 2 pulse outputs (CW / CCW)	
ΞĘ	High-speed	Countable range	-1,073,741,823 to +1,073,741,823 pulse	
Other specifications	counter function (Note)	Input mode	Phase difference input, Direction distinction input, Individual input (transfer multiple available for each)	
₹	Built-in servo ON output			

Note: Pulser input and high-speed counter functions cannot be used simultaneously, as the same pulse input terminal is used.

### **PULSE OUTPUT UNITS**



### Super high-speed positioning control achieved

### **High-speed startup**

The pulse output request is received from the CPU unit and the startup speed up to output of the pulse is super high-speed of 1 µs. Tact time is reduced with repeat of short-distance positioning operations, etc.



Pulse output unit

Index table

### Neater wiring to servo and amplifier

Equipped with a servo ON output terminal, wiring to the servo amplifier is neater.

### Replacement from FP2 series is easy

Usage is same as the previous FP2 positioning unit (multifunction type). Program transfer is easy.

### SPECIFICATIONS

	Item	AFP7PG02T	AFP7PG04T	AFP7PG02L	AFP7PG04L	
CE marking directive compliance		EMC Directive, RoHS Directive				
Output type	С соприспос	Transistor Line driver			driver	
Occupied points		Each 32 points of I/O			Each 64 points of I/O	
Number of axes cor	ntrolled	2 axes, independent	4 axes, independent	Each 32 points of I/O 2 axes, independent	4 axes, independent	
	Command units	· · ·	(The program specifies whet	, ·	, <u>'</u>	
Position command	Max. pulse count		Signed 32 bits (+2,147,483,6			
Speed command	Command range		s (can set in 1 pps)		(can set in 1 pps)	
'	Acceleration / deceleration		near acceleration / deceleration		11 /	
Acceleration / deceleration	"S" Acceleration / deceleration		lect from sin curve, secondar			
command	Acceleration / deceleration time			(can set in 1 ms)		
	Home return speed	Spe	eed setting possible (changes	,	eed)	
Home return	Input signal	Home input, near home input, limit input (+), limit input (-)				
	Output signal	Deviation counter clear signal				
Operation mode		E point control (linear and S acceleration / decelerations) P point control (linear and S acceleration / decelerations) Home return operation (home search) JOG operation (Note 1) JOG positioning operation Pulser input function (Note 2) transfer multiplication ratio (× 1, × 2, × 5, × 10, × 50, × 100, × 500, × 1,000) Real-time frequency change Infinity output				
Startup time		0.02 ms, 0.005 ms or 0.001 ms selecting possible (Note 3)				
Output interface	Output mode	1 pulse output (pulse and sign), 2 pulse output (CW and CCW)				
High-speed counter	Countable range	Signed 32 bits (+2,147,483,647 to -2,147,483,648 pulse)				
function (Note 2)	Input mode	Two-phase inpu	it, direction distinction input, i	ndividual input (with multiplier	function mode)	
Other functions		Startup using I/O contact Built-in limit (+) and limit (-) With servo ON output				
External power	Voltage		21.6 to 2	6.4 V DC		
supply	Current	50 mA (at 24 V)	90 mA (at 24 V)	50 mA (at 24 V)	90 mA (at 24 V)	

Notes: 1) When linear acceleration / deceleration operation is selected, it is possible to change the target speed during operation.

2) Since the pulsar input function and the high-speed counter function use the same pulse input terminal, both functions cannot be used at the same time.

3) Startup time can be changed using the common memory control code setting. The factory (default) setting is 0.02 ms. Startup time is defined as the time between startup and output of the first pulse.

LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS

SENSOR OPTIONS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

FA COMPONENTS

MACHINE

VISION SYSTEMS

Applications

Software

Program Transfer Others

FP-X0 FP0R

FPΣ FP-X

FP2SH

LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

SENSORS

PARTICULAR
USE
SENSORS

SENSOR OPTIONS SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS MEASURE-MENT SENSORS

SENSORS STATIC CONTROL DEVICES

LASER MARKERS

INTERFACES

ENERGY
MANAGEMENT
SOLUTIONS

HUMAN

COMPONENTS MACHINE

VISION SYSTEMS UV CURING SYSTEMS

Applications

Program Transfer Others

FP-X0
FP0R
FP2
FP-X
FP2SH

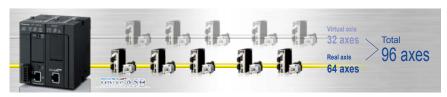
FP-e

### MOTION CONTROL UNIT EtherCAT TYPE



Motion control of up to 64 axes in one unit

Control 64 axes of Panasonic servo motor MINAS A6B / A5B and 32 virtual axes. It is now easier to perform multiple axial control



- Up to 32 synchronous groups! (32 groups of 2 axes to 2 groups of 32 axes)
- Industry's fastest class with 0.5 ms\* control cycle
- · Control system: Cyclic position control
- Positioning table: 1,000 tables/axis
- \*4 axes (2-axis interpolation × 2 groups). Our company created send/receive allocation.

### SPECIFICATIONS

					10 '	00 1	0.4					
Item				16 axes type								
CE	CE marking directive compliance			ompliance	EMC Directive, RoHS Directive							
Со	Connected slave (Note 1, 2, 3)			te 1, 2, 3)		rvo motor MINAS . S-LINK V gateway co	ntroller SL-VGU1-EC					
					Real axis:	Real axis:	Real axis:					
Nu	mbe	er o	f control a	axes	16 axes Virtual axis:	32 axes Virtual axis:	64 axes Virtual axis:					
					8 axes	16 axes	32 axes					
Со	mm	uni	cation cyc	cle		s / 1 ms / 2 ms						
Int	erpo	olati	on contro	ol		polation, 2-axis circu polation and 3-axis						
Nu	mbei	of c	occupied I/0	O points	Input: 16	points, Output:	16 points					
		Pos	ition specifica	tion method		pecified absolu (specified relati						
		Po	sition spec	cified unit	pulse  pum (select a minimum instruction unit of 0.1 µm or 1 µm)  inch (select a minimum instruction unit of 0.00001 inch or 0.0001 inch)  degree (select a minimum instruction unit of 0.1 degree or 1 degree)							
		Pos	sition refere	nce range	μm (0.1 μm): -214,7 μm (1 μm): -2,147,4 inch (0.00001 inch) inch (0.0001 inch): degree (0.1 degree)	48 to 2,147,483,647 pr 48,364.8 to 214,748,83,648 to 2,147,483,648 to 2214,748.3648 to 214,748.3648 to 214,748.3648 to 214,748.3648 to 2,147,483,648 to 2,147,483,648 to 2,147,483,648 to 2,1447,483,648 to 2,1447	364.7 µm 647 µm 1,474.83647 inch 1,748.3647 inch 114,748,364.7 degree					
uo	(SP)	Spe	eed referen	ce range	pulse: 1 to 2,147,483,647 pps µm: 1 to 2,147,483,647 µm/sec. inch: 0.001 to 2,147,483.647 inch/sec. degree: 0.001 to 2,147,483.647 rev/sec.							
erati	<u>0</u>	Acceleration / deceleration type			Linear acceleration / deceleration, S-shaped acceleration / deceleration							
do	ont		celeration	- 7 1	0 to 10,000 ms							
Ę	o o	deceleration			(adjustable in 1 ms increments)							
Automatic operation	Positioning control (CSP)		Number of positioning tables		expansion are	tandard area: 1 a 100 points (2 g simultaneous	4 axes in case					
	A.		Indepen	dent	PTP control (E point cor Speed control (J point co	ntrol, C point control), CP ( ontrol)	control (P point control),					
		Control method	2-axis	Linear interpolation		t and C point co						
			interpolation  3-axis interpolation	Control me	trol me	trol me	rol me	interpolation	Circular interpolation	E point, P point Center point of	t and C point cor r passing point	ontrols:
						Linear interpolation		t and C point co				
				Spiral interpolation		nt and C point or passing point						
			her nction	Dwell time	0 to 32,767 ms	(adjustable in 1	ms increments)					

Notes: 1) A6B and **SL-VGU1-EC** are compatible with the **FP7** motion control unit Ver.1.2 or later.

- 2) One unit or more of A6B or A5B must exist on the network.

  A6B and A5B can be used together.
- 3) The hub for EtherCAT / Ethernet cannot be used.

	Item			16 axes type 32 axes type 64 axes type	
	JOG /	Speed reference range		pulse: 1 to 2,147,483,647 pps µm: 1 to 2,147,483,647 µm/sec. inch: 0.001 to 2,147,483.647 inch/sec. degree: 0.001 to 2,147,483.647 rev/sec.	
_	operation	Acceleration / deceleration type		Linear acceleration / deceleration, S-shaped acceleration / deceleration	
ration			leration / leration time	0 to 10,000 ms (adjustable in 1 ms increments)	
Manual operation		Speed reference range		pulse: 1 to 2,147,483,647 pps µm: 1 to 2,147,483,647 µm/sec. inch: 0.001 to 2,147,483.647 inch/sec. degree: 0.001 to 2,147,483.647 rev/sec.	
Σ	Home return		eleration / eleration type	Linear acceleration / deceleration, S-shaped acceleration / deceleration	
			eleration / eleration time	0 to 10,000 ms (adjustable in 1 ms increments)	
		Retu	ırn methods	DOG method (4 types), Limit method (2 types), Data set method, Z phase method, Stop-on-contact method (2 types)	
n	Deceleration	n stop	Deceleration time	Axis operation mode startup time of activated axis	
Stop function	Emergeno	y stop	Deceleration time	0 to 10,000 ms (adjustable in 1 ms increments)	
fu	Limit st	ор	Deceleration time	0 to 10,000 ms (adjustable in 1 ms increments)	
d	Error st	op	Deceleration time	0 to 10,000 ms (adjustable in 1 ms increments)	
Š	System	stop	Deceleration time	Immediate stop (1 ms), all axes stop	
	Synchronous basic setting		Master axis	Selection possible of real axis and virtual axis	
nctio			Slave axis	Virtual axis: Virtual axis: Virtual axis: Wirtual axis: Max. 8 axes/master Max. 16 axes/master Max. 32 axes/master	
Ę	Electronic gear function		Operation setting	Gear ratio setting	
흪			Operation method	Direct method, Acceleration / deceleration method	
era			Clutch ON trigger	Contact input	
g	function		Clutch method	Direct method, Linear slide method	
Synchronous operation function	Electronic cam function		Cam curve	Select from 20 types Multiple curves can be specified within a phase (0 to 100 %).	
ř			Resolution	1,024, 2,048, 4,096, 8,192, 16,384, 32,768	
Sync			Number of cam patterns	16 to 64 32 to 128 64 to 256 (Depends on resolution) (Depends on resolution)	
suo	Software limit function		Set range	pulse: -2,147,483,648 to 2,147,483,647 pulse µm (0.1 µm): -214,748,364.8 to 2,147,483,64.7 µm µm (1 µm): -2,147,483,648 to 2,147,483,647 µm inch (0.00001 inch): -21,474,83648 to 21,474,83647 inch inch (0.0001 inch): -214,748,3648 to 21,474,83647 inch degree (0.1 degree): -214,748,364.8 to 214,748,364.7 degree degree (1 degree): -2,147,483,648 to 2,147,483,647 degree	
ecificati	Monitor judgment		Torque judgment	Torque judgment Selection possible of active / non-active and error / warning 0.0 to ±500.0 %	
Other specifications			Actual speed judgment	Actual speed judgment Selection possible of active / non-active and error / warning 0.0 to ±5,000 rpm	
J	Backup	)		Parameters and positioning data are saved to flash memory (battery free)	
	General-purpose input: 5 p		pose input: 5 po	L monitor and proximity (DOG) monitor pints, General-purpose output: 1 point (I/O from AMP) and auxiliary output cord	
Cur	rent consu	umptio	n (at 24 V DC)	180 mA approx.	
We	eight			150 g approx.	

### **POWER SUPPLY UNITS**



# Announce system errors using the built-in external alarm

### **Equipped with system error alarm contact**

Output contact for system error external alarm is provided. If a power supply unit is used concurrently, no additional units are required.

SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING

WIRE-SAVING

MEACURE

MEASURE-MENT SENSORS

CONTROL DEVICES

LASER MARKERS

PLC

MACHINE INTERFACES

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS

MACHINE VISION SYSTEMS

> V URING YSTEMS

Applications

Program Transfer

Others

FP7

FP-X0 FP0R

FPΣ FP-X

FP2SH

FP-e

### SPECIFICATIONS

Item	AFP7PSA1	AFP7PSA2
CE marking directive compliance	EMC Directive, Low Voltage	Directive, RoHS Directive
Rated input voltage	100-240	VAC
Allowable input voltage range	85-264	VAC
Input power supply frequency 47 to 63 Hz		
Inrush current	40 A or less (Note 2)	
Input current	0.75 A or less	1.25 A or less
Rated output current (at 24 V)	1.0 A	1.8 A
Alarm contact capacity	1 A (30 V DC)	
Remaining lifespan counting function	Not available	Available (Note 1)

Notes: 1) Alarm by CPU unit

2) On cold starting

3) Power supply unit cannot be used with AFP7CPS21 CPU unit.

### **SERIAL COMMUNICATION UNIT**



# Lineup of serial communication unit that can be expanded with a serial communication cassette

# Two serial communication add-on cassettes can be installed

A total of five types of cassettes can be freely combined in a combination of RS-232C, RS-422 or RS-485. Up to 4 channels can be supported in one unit.

### **High expandability**

The number of serial communication channels can be increased by connecting a CPU unit. A CPU unit can be connected to maximum of 8 serial communications units.

Note: To connect serial communication unit, the CPU unit has to have firmware Ver. 1.2 or later, and to be running **FPWIN GR7** Ver. 1.3 or later

### SPECIFICATIONS

Item	AFP7NSC
CE marking directive compliance	EMC Directive, RoHS Directive
Number of communication cassette installations	Max. 2 cassettes
Number of installations to CPU unit	Max. 8 units

PHOTO-ELECTRIC SENSORS

PHOTO-ELECTRIC SENSORS AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS SIMPLE WIRE-SAVING UNITS

WIRE-SAVING SYSTEMS MEASURE-MENT SENSORS

SENSORS STATIC CONTROL DEVICES

LASER MARKERS

HUMAN MACHINE INTERFACES

MANAGEMENT SOLUTIONS FA COMPONENTS

MACHINE VISION

VISION SYSTEMS UV CURING SYSTEMS

Applications
PLC
Software

Program Transfer Others

> FP-X0 FP0R FPΣ

FP-X FP2SH FP-e

### PHLS (REMOTE I/O) UNITS



# Speedy, resistant to noise Remote I/O Line up

### **High speed communication**

A 12 Mbps maximum transmission speed can be selected. Fast response at update cycle of 1,000 points/2 ms can be achieved.

### High resistance to noise

Data can be transferred accurately, even in inadequate wiring environments.

### Various types of compact slave units

Compact slave units (60 × 70 × 40 mm 2.36 × 2.76 × 1.57 in) are smaller than common screw terminal types and are lined up to contribute to space savings. A wide variety of slave units are available.

### **SPECIFICATIONS**

### **Communication specifications (common)**

Item	Specifications
Communication method	Two-wire system half duplex
Insulation method	Pulse transformer insulation
Communication speed	6 Mbps / 12 Mbps
Synchronous method	Bit synchronization
Error check	CRC-12
Communication distance	Total length 200 m 656 ft (at 6 Mbps) / 100 m 328 ft (at 12 Mbps) (Note)
Connection method	Multi-drop method
Impedance	100 Ω
Terminator	Mounted on unit
External interface	Master unit: terminal block (2 channels) Slave unit (standard type): screw-type terminal block Slave unit (compact type): connector-type terminal block

Note: Performance when the recommended cable is used. Use of the recommended cable is necessary to achieve the maximum transmission distance and number of slave units.

### **Output side specifications (except relay)**

Item		Specifications		
		Standard type	Compact type (except relay)	
Insulation method		Photocoupler	Non-isolated	
Output typ	e	Sink type (Open	collector output)	
Rated load	d voltage	20.4 to 2	8.8 V DC	
Max. contr	ol capacity	0.1 A/point		
Max. surg	e current	0.5 A		
OFF state lea	akage current	0.1 mA or less		
ON state maxim	num voltage drop	0.5 V or less		
Repose	OFF→ON	0.05 ms or less		
time	ON→OFF	0.5 ms	or less	
Surge absorber		Zener diode		
Short circuit protection		None		

### Input side specifications

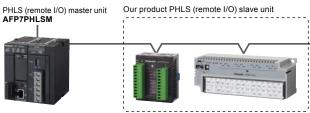
Item		Specifications		
		Standard type	Compact type	
Insulation	method	Photocoupler	Non-isolated	
Rated inpu	ıt voltage	24 V DC		
Rated input current		3 mA approx.	4.3 mA approx.	
Input impedance		7.5 kΩ approx.	5.6 kΩ approx.	
Min. ON voltage / Min. ON current		15 V / 2 mA	17 V / 2 mA	
Max. OFF voltage / Max. OFF current		5 V / 0.5 mA		
Response	OFF→ON	1 ms (	or less	
time	ON→OFF	1 ms or less		

### Output side specifications (relay)

	_		
Item		Specifications	
		Compact type (relay)	
Insulation	method	Relay insulation	
Rated conti	rol capacity	1 A 250 V AC (2 A/common), 1 A 30 V DC (2 A/common)	
Min. load		0.1 mA, 100 mV (resistive load)	
Repose	OFF→ON	10 ms or less	
time	ON→OFF	5 ms or less	
	Mechanical life	2 × 10 <sup>7</sup> operations or more	
Life time	Electrical life	1 × 10 <sup>5</sup> operations or more (switching frequency: 20 times/minute)	
Surge absorber		None	
Short circuit protection		None	

### Introduction of remote analog units

Our PHLS (remote I/O) unit complies with HLS (Hi-speed Link System) specification. This product is used when you want to connect analog units from other manufacturers that comply with the HLS specification.



Other companies' analog units compliant with HLS (Hi-speed Link System)



M-System Co., Ltd.

DC voltage / current input, 4 points R7HL-SV4-R/H DC voltage output, 2 points R7HL-YV2-R/H

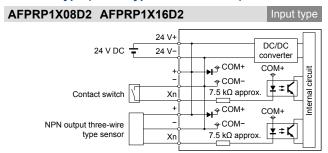
Notes: 1) When using another company's HLS-compliant product, be sure to verify that the units operate correctly with the installed target equipment. Please contact the respective manufacturers for product details.

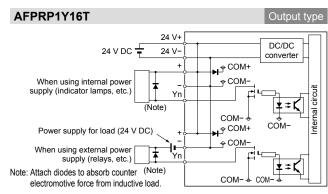
Units other than the analog units shown above can also be connected. The following shows the communication specifications of our PHLS (remote I/O) master unit. Please select a unit that meets the specifications.

Communication method	Transmission speed	Connection method
Half-duplex communication (incompatible with full-duplex communication)	6 Mbps / 12 Mbps	Terminal block (connection via screw terminal)

### I/O CIRCUIT DIAGRAMS

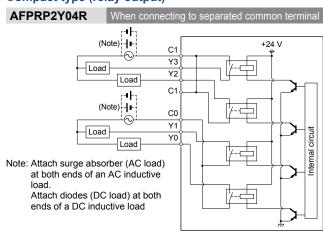
### Standard type (screw-type terminal block)





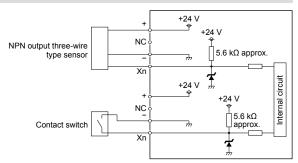
### AFPRP1XY16D2T I/O mixed type 24 V+ DC/DC 24V DC 🛨 24 V-►+ COM+ COM+ . ⊕COM-Contact switch 7.5 kΩ approx. Xn ► COM+ g COM− When using internal power supply (indicator lamps, etc.) |¥≠K Note: Attach diodes to absorb counter COMelectromotive force from inductive load.

### Compact type (relay output)

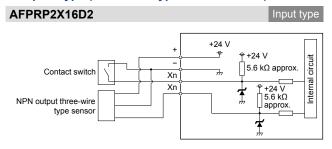


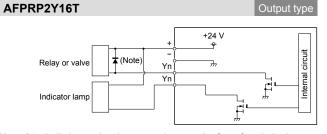
### Compact type (e-CON)

### AFPRP2X08D2E



### Compact type (connector-type terminal block)

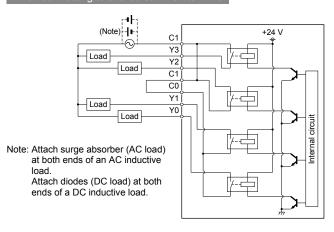




Note: Attach diodes to absorb counter electromotive force from inductive load.

### AFPRP2XY16D2T I/O mixed type +24 V +24 V 5.6 kΩ approx. Contact switch Χn † +24 V 5.6 kΩ approx Xn NPN output three-wire type sensor Internal circuit +24 V (Note) Relay or valve 7 Υn Yn Indicator lamp Note: Attach diodes to absorb counter electromotive force from inductive load.

### When connecting to shared common terminal



FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

PARTICULAR USE SENSORS SENSOR OPTIONS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

ENERGY MANAGEMENT SOLUTIONS

FA COMPONENTS MACHINE

VISION SYSTEMS UV CURING SYSTEMS

Applications Software

Program Transfer Others

FP-X0

FP0R FPΣ FP-X

FP2SH

LASER SENSORS PHOTO-ELECTRIC SENSORS

AREA SENSORS SAFETY LIGHT CURTAINS / SAFETY COMPONENTS

PRESSURE / FLOW SENSORS INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS

SENSOR OPTIONS SIMPLE WIRE-SAVING UNITS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES LASER MARKERS

FA COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Applications Software Program Transfer Others

FP-X0 FP0R FPΣ FP-X FP2SH FP-e

### **COMMON GENERAL SPECIFICATIONS**

Item	Specifications
Ambient temperature	0 to +55 °C +32 to +131 °F, Storage: -40 to +70 °C -40 to +158 °F
Ambient humidity	10 to 95 % RH (at +25 °C +77 °F, no dew condensation allowed), Storage: 10 to 95 % RH (at +25 °C +77 °F, no dew condensation allowed)
Breakdown voltage	500 V AC for 1 minute (Note 2) (Note 3)
Insulation resistance	100 MΩ or more (at 500 V DC)
Vibration resistance	5 to 8.4 Hz, single amplitude of 3.5 mm 0.138 in, 1 sweep / 1 min. (IEC61131-2), 8.4 to 150 Hz, constant acceleration of 9.8 m/s², 1 sweep / 1 min. (IEC61131-2), 10 times each in X, Y, and Z directions
Shock resistance	147 m/s² or more , 3 times each in X, Y, and Z directions (IEC61131-2)
Noise immunity	1,000 V [p-p] with pulse width 50 ns and 1 µs (using a noise simulator)
Operating condition	Free from corrosive gasses and excessive dust

- Notes: 1) Please refer to the unit's specification sheet for details of breakdown voltage and insulation resistance.

  - 2) Relay output of input and output unit: 2,300 V AC for 1 minute
    3) Between analog input channels of analog input unit: 200 V AC for 1 minute Between channels of output unit: non insulation

### INDIVIDUAL GENERAL SPECIFICATIONS

Item		CPU	Expansion units				
item	AFP7CPS41E(S)	AFP7CPS31E(S)	AFP7EXPM AFP7EXPS				
Rated voltage range		20.4 to 28			20.4 to 28.8 V DC		
Current consumption		200 mA or less		150 mA or less	120 mA or less	100 mA or less	
Naturialit		220 g approx.	180 g approx.	400	200 g approx.		
Net weight		(with terminal blo	ck and end unit)		120 g approx.	200 g approx. (with end unit)	

Item		Communication cassettes							Function cassettes			
nem	AFP7CCS1	AFP7CCS2	AFP7CCM1	AFP7CCM2	AFP7CCS1M1	AFP7CCET1	AFP7FCAD2	AFP7FCA21	AFP7FCTC2			
Rated voltage range												
Current consumption	35 mA or less (Note)	60 mA or less (Note)	60 mA or less (Note)	90 mA or less (Note)	70 mA or less (Note)	35 mA or less (Note)	40 mA or less (Note)	75 mA or less (Note)	45 mA or less (Note)			
Net weight		25 g approx. (with terminal block) 20 g					25 g app	rox. (with termin	nal block)			

Item		Digital input and output units										
nem	AFP7X16DW	AFP7X32D2	AFP7X64D2	AFP7Y16R	AFP7Y16T	AFP7Y32T	AFP7Y64T	AFP7Y16P	AFP7Y32P	AFP7Y64P	AFP7XY64D2T	AFP7XY64D2P
Rated voltage range												
Current consumption	25 mA or less	30 mA or less	35 mA or less	180 mA or less	35 mA or less	50 mA or less	75 mA or less	35 mA or less	50 mA or less	75 mA or less	55 mA or less	55 mA or less
Net weight	125 g approx.	95 g approx.	110 g approx.	180 g approx.	125 g approx.	95 g approx.	115 g approx.	125 g approx.	95 g approx.	115 g approx.	115 g approx.	115 g approx.

Item	Analog input and output units			Temperatur	Temperature input units		Multi input and output unit		High-speed counter units	
nem	AFP7AD4H	AFP7DA4H	AFP7AD8	AFP7TC8	AFP7RTD8	AFP7MXY32DWD	AFP7MXY32DWDH	AFP7HSC2T	AFP7HSC4T	
Rated voltage range										
Current consumption	100 mA or less	250 mA or less	85 mA or less	80 mA or less	65 mA or less	100 mA or less	100 mA or less	65 mA or less	65 mA or less	
Net weight	130 g approx.	130 g approx.	130 g approx.	145 g approx.	145 g approx.	100 g approx.	100 g approx.	130 g approx.	130 g approx.	

Item	Positioning units			Pulse output units			Motion control unit			Serial communication unit	Power	supply its		
	AFP7PP02T	AFP7PP04T	AFP7PP02L	AFP7PP04L	AFP7PG02T	AFP7PG04T	AFP7PG02L	AFP7PG04L	AFP7MC16EC	AFP7MC32EC	AFP7MC64EC	AFP7NSC	AFP7PSA1	AFP7PSA2
Rated voltage range													100-24	0 V AC
Current consumption	120 mA or less	120 mA or less	120 mA or less	120 mA or less	65 mA or less	65 mA or less	65 mA or less	65 mA or less	180 mA approx.	180 mA approx.	180 mA approx.	50 mA or less (when without add-on cassette)	750 mA or less	1,250 mA or less
Net weight	145 g approx.	145 g approx.	145 g approx.	145 g approx.	130 g approx.	150 g approx.	130 g approx.	150 g approx.	150 g approx.	150 g approx.	150 g approx.	110 g approx.	240 g approx.	290 g approx.

Item	PHLS (remote I/O) units									
	AFP7PHLSM	HLSM AFPRP1X08D2 AFPRP1X16D2 AFPRP1Y16T AFPRP1XY16D2T AFPRP2X08D2E AFPRP2X16D2 AFPRP2Y16T AFPRP2XY16D2T AFPRP2Y04R								
Rated voltage range			20.4 to 28.8 V DC							
Current consumption	85 mA or less	100 mA or less	150 mA or less	75 mA or less	120 mA or less	100 mA or less	170 mA or less	40 mA or less	110 mA or less	85 mA or less
Net weight	110 g approx.	140 g approx.	210 g approx.	210 g approx.	210 g approx.	75 g approx.	75 g approx.	75 g approx.	75 g approx.	75 g approx.

Note: This value is the increase in CPU unit current consumption.

### PRODUCT TYPES

### **CPU** units

Prod	uct name	Standard program capacity	Max. program capacity	Operation speed	Ethernet function (Note 2)		Encryption function (Note 3) (Note 4)	Part No.
		196 k steps	234 k steps	From 11 ns	Built-in	Built-in		AFP7CPS41E
		120 k steps	120 k steps	From 11 ns	Built-in	Built-in		AFP7CPS31E
		120 k steps	120 k steps	From 11 ns		Built-in		AFP7CPS31
FP7 CPU units		196 k steps	234 k steps	From 11 ns	Built-in	Built-in	Built-in	AFP7CPS41ES
	Security enhanced type	120 k steps	120 k steps	From 11 ns	Built-in	Built-in	Built-in	AFP7CPS31ES
		120 k steps	120 k steps	From 11 ns		Built-in	Built-in	AFP7CPS31S
	Best value model	64 k steps	64 k steps	From 14 ns				AFP7CPS21

Notes: 1) One end unit is attached to the CPU unit.

- 1) One end unit is attached to the CPO unit.
   2) Ethernet function includes FTP server / client function, Web server function, HTTP client function, E-mail sending function and EtherNet/IP compatibility. Ethernet is a registered trademark of Fuji Xerox Co., Ltd. and Xerox Corporation. Ethernet/IP is a trademark of ODVA.
   3) When exporting to China, please use a CPU unit that does not have an encryption function.
   4) For CPU units with encryption function, please use the security enhanced type programming tools.

### **Expansion units**

Product name	Specifications	Part No.
FP7 expansion master unit	Expansion of up to 3 slave units possible	AFP7EXPM
FP7 expansion slave unit (Note 1)	Up to 16 units can be connected to 1 slave unit.	AFP7EXPS
	Length: 0.5 m 1.640 ft	AFP7EXPCR5
Expansion cables	Length: 1 m 3.281 ft	AFP7EXPC01
Expansion cables	Length: 3 m 9.843 ft	AFP7EXPC03
	Length: 10 m 32.808 ft	AFP7EXPC10

Notes: 1) One end unit is attached to the expansion slave unit.
2) Expansion unit cannot be used with the **AFP7CPS21** CPU unit.

### Add-on cassettes

Product name	Specifications	Part No.
	RS-232C, 1 channel (insulated)	AFP7CCS1
	RS-232C, 2 channels (insulated)	AFP7CCS2
	RS-422 or RS-485, 1 channel (insulated)	AFP7CCM1
FP7 communication cassettes	RS-422 or RS-485, 2 channels (insulated)	AFP7CCM2
	RS-232C, 1 channel (insulated) and RS-485, 1 channel (insulated)	AFP7CCS1M1
	Ethernet 100Base-TX / 10Base-T	AFP7CCET1
	Analog input, 2 channels, voltage / current	AFP7FCAD2
FP7 function cassettes	Analog input and output, input: 2 channels, output: 1 channel	AFP7FCA21
	Thermocouple input, 2 channels K / J	AFP7FCTC2

### Power supply units

Product name	Input specifications	Output specifications	Other functions	Part No.
FP7 power	100-240 V AC	24 V DC, 1.0 A	System error alarm output contact	AFP7PSA1
supply units	100-240 V AC	24 V DC, 1.8 A	System error alarm output contact and remaining lifespan counting function	AFP7PSA2

Note: Power supply unit cannot be used with the AFP7CPS21 CPU unit.

### Input and output units

Product name	Туре	Number of points	Connection method	Specifications	Part No.
		16 points	Terminal block	12 to 24 V DC, common polarity: +/- common, input time constant setting	AFP7X16DW
FP7 input units	DC input	32 points	MIL connector	24 V DC, common polarity: +/- common, input time constant setting	AFP7X32D2
		64 points	MIL connector	24 V DC, common polarity: +/- common, input time constant setting	AFP7X64D2
	Relay output		Terminal block	2 A/point, 5 A/common, 16 points/common (without relay socket)	AFP7Y16R
		16 points	Terminal block	Load current: 1.0 A, 5 A/common, 16 points/common	AFP7Y16T
	Transistor output, sink (NPN)	32 points	MIL connector	Load current: 0.3 A, 3.2 A/common, 32 points/common	AFP7Y32T
FP7 output units		64 points	MIL connector	Load current: 0.3 A / 0.1 A mixed, 3.2 A /common, 32 points/common	AFP7Y64T
		16 points	Terminal block	Load current: 1.0 A, 5 A/common, 16 points/common	AFP7Y16P
	Transistor output, source (PNP)	32 points	MIL connector	Load current: 0.3 A, 3.2 A/common, 32 points/common	AFP7Y32P
		64 points	MIL connector	Load current: 0.3 A / 0.1 A mixed, 3.2 A /common, 32 points/common	AFP7Y64P
FP7 input and output mixed DC	DC input transistor output, sink (NPN)	Input: 32 points Output: 32 points	MIL connector	Input: 24 V DC, 32 points/common Output: load current: 0.3 A / 0.1 A mixed, 3.2 A/common, 32 points/common	AFP7XY64D2T
	DC input transistor output, source (PNP)	Input: 32 points Output: 32 points	MIL connector	Input: 24 V DC, 32 points/common Output: load current: 0.3 A / 0.1 A mixed, 3.2 A/common, 32 points/common	AFP7XY64D2P

### Analog input and output units

Product name	Specifications	Number of channels	Part No.
FP7 analog input unit (High-speed and multi-channel type)	Voltage / current, conversion rate: 25 µs/channel, resolution: max. 16 bits, accuracy: ±0.1 % F.S. or less (at +25 °C +77 °F)	8 channels	AFP7AD8
FP7 analog input unit (High-speed and high-accuracy type)	Voltage / current, conversion rate: 25 µs/channel, resolution: max. 16 bits, accuracy: ±0.05 % F.S. or less (at +25 °C +77 °F), insulation between channels	4 channels	AFP7AD4H
FP7 analog output unit (High-speed and high-accuracy type)	Voltage / current, conversion rate: 25 µs/channel, resolution: max. 16 bits, accuracy: ±0.05 % F.S. or less (at +25 °C +77 °F), insulation between channels	4 channels	AFP7DA4H

Note: Please note that the digital converted value corresponding to about 2 V of analog input is stored in the input relay area (WX) for channels which are not connected to input when setting the voltage range with **AFP7AD8**.

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Applications Software

# FP2SH

FP-e

### PRODUCT TYPES

### Temperature input units

Product name	Specifications	Number of channels	Part No.
	Thermocouple (K, J, T, N, R, S, B, E, PLII and WRe5-26), voltage / current, conversion rate: 5 ms/channel, resolution: max. 16 bits, accuracy: ±0.1 % F.S. (at +25 °C +77 °F), insulation between channels	8 channels	AFP7TC8
	Resistance temperature detector (Pt100, JPt100 and Pt1000), conversion rate: 25 ms/channel, accuracy: $\pm 0.1$ % F.S. (at +25 °C +77 °F), insulation between channels	8 channels	AFP7RTD8

Note: The temperature input units are compatible with the FP7 CPU units with firmware of Ver. 2.0 or later on p. 1288. The compatible version of Control FPWIN GR7 is 2.2 or later.

### Multi input and output unit

Product name			Specifications			
		Number of points	Connection method	Functions	Part No.	
FP7 multi input and output unit  Positioning type		Innut: 16 noints		Input: total 16 points, DC input: max. 16 points, high-speed counter: max. 4 channels (1 channel: 4 points), interrupt input: max. 8 points Output: total 16 points, transistor output: max. 16 points, pulse output:	AFP7MXY32DWD	
		Output: 16 points	MIL connector	max. 4 channels (Note) (1 channel: 2 points), PWM output: max. 4 channels (1 channel: 1 points), comparison output: max. 8 points, positioning: max. 4 channels (AFP7MXY32DWDH only)	AFP7MXY32DWDH	

Note: Trapezoidal control with acceleration / deceleration not yet supported.

### **High-speed counter units**

Droduct name		Part No.			
Product name	Input time constant	Number of counters	Counter type	Input type	Fait No.
ED7 high around country units	Selection type	2 channels	Liner counter / ring counter	Individual input: 1 multiple, 2-multiple Direction discrimination input: 1 multiple, 2-multiple 2-phase input: 1 multiple, 2-multiple, 4-multiple	AFP7HSC2T
FP7 high-speed counter units	Selection type	4 channels	Liner counter / ring counter	Individual input: 1 multiple, 2-multiple Direction discrimination input: 1 multiple, 2-multiple 2-phase input: 1 multiple, 2-multiple, 4-multiple	AFP7HSC4T

### **Positioning units**

Product name		Part No.				
Product name	Output type	Number of axes controlled	Operation speed	Functions	Fait No.	
	Transistor	2 axes	1 pps to 500 kpps		AFP7PP02T	
ED7 nacitioning units	Hansistoi	4 axes	i pps to 500 kpps	Electronic cam and electronic gear	AFP7PP04T	
FP7 positioning units	Line driver	2 axes	1 nno to 4 Mnno	functions, linear interpolation, circular interpolation	AFP7PP02L	
	Line driver	4 axes	1 pps to 4 Mpps	Silvara interpolation	AFP7PP04L	

### **Pulse output units**

Product name	Specifications				
Floduct flame	Output type	Number of axes controlled	Operation speed	Part No.	
FP7 pulse output units	Transistor	2 axes	1 pps to 500 kpps	AFP7PG02T	
	Transistor	4 axes	i pps to 500 kpps	AFP7PG04T	
	Line driver	2 axes	1 ppo to 4 Mppo	AFP7PG02L	
	Line driver	4 axes	1 pps to 4 Mpps	AFP7PG04L	

### **Motion control units**

Due duet name	Numbe	Dort No.	
Product name	Real axis	Virtual axis	Part No.
FP7 motion control unit EtherCAT type	16	8	AFP7MC16EC
	32	16	AFP7MC32EC
	64	32	AFP7MC64EC

<sup>\*</sup>EtherCAT is trademark or registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

### Serial communication unit

Product name	Number of communication cassette	Number of installations of CPU unit	Part No.
FP7 serial communication unit	Max. 2 cassettes	Max. 8 units	AFP7NSC

### PHLS (remote I/O) master unit

Product name	Max. points	Communication speed	Total distance	Max. number of connections	Part No.
FP7 PHLS master unit	1,008 points	6 Mbps / 12 Mbps	200 m 656 ft (at 6 Mbps) / 100 m 328 ft (at 12 Mbps)	63 slaves	AFP7PHLSM

### PRODUCT TYPES

### PHLS (remote I/O) slave units

Product name	Shape	Connection method	Туре	Number of points	Specifications	Part No.
			DC input	8 points	24 V DC, common polarity: +, 8 points/common	AFPRP1X08D2
Stand type			DC input	16 points	24 V DC, common polarity: +, 16 points/common	AFPRP1X16D2
	Standard type	Screw-type terminal block	Transistor output (sink)	16 points	Load current: 0.1 A, common polarity: -, 0.4 A/common, 16 points/common	AFPRP1Y16T
		DIOOR	DC input transistor output (sink)	Input: 8 points Output: 8 points	Input: 24 V DC, common polarity: +, 8 points/common Output: load current: 0.1 A, common polarity: -, 0.4 A/common, 8 points/common * Input / output common is shared.	AFPRP1XY16D2T
FP7 PHLS slave units		' I. I	DC input	8 points	24 V DC, common polarity: +, 8 points/common	AFPRP2X08D2E
			DC input	16 points	24 V DC, common polarity: +, 16 points/common	AFPRP2X16D2
	Compact		Transistor output (sink)	16 points	Load current: 0.1 A, common polarity: -, 0.8 A/common, 16 points/common	AFPRP2Y16T
	type		Transistor output (sink)	Input: 8 points Output: 8 points	Input: 24 V DC, common polarity: +, 8 points/common Output: load current: 0.1 A, common polarity: -, 0.8 A/common, 8 points/common * Input / output common is shared.	AFPRP2XY16D2T
			Relay output	4 points	1 A / 1 point, 2 A/common, 2 points/common	AFPRP2Y04R

### **Option**

Product name	Specifications	Part No.		
FP-X backup battery (Common to FP-X)	FP-X backup battery (Common to FP-X) Battery for back up of clock / calendar operation			

### **Programming tools**

Pro	duct	name	Туре	Specifications	Part No.
	Japa	nese version	Supports only CPU without encryption function		AFPSGR7JP
Programming software for		Security enhanced type	Supports both CPU with/without encryption function	VVINdows°8.1 (32-bit / 64-bit) /	AFPSGR7JPS
	English version		Supports only CPU without encryption function	***************************************	AFPSGR7EN
FPWIN GR7		Security enhanced type	Supports both CPU with/without encryption function	Windows® Vista SP2 / XP SP3	AFPSGR7ENS
Programming software for		ish, Japanese, an and Chinese	Supports all <b>FP</b> series PLCs ( <b>FP7</b> series: supports only CPU without encryption function)	Windows®10 (32-bit / 64-bit) / Windows®8.1 (32-bit / 64-bit) /	AFPSPR7A
Windows® Control FPWIN Pro7		Security enhanced type	Supports all FP series PLCs (FP7 series: supports both CPU with/without encryption function) * The encryption function will be offered in the future.	Windows® (32-bit / 64-bit) / Windows®7 SP1 or more (32-bit / 64-bit) / Windows® Vista SP2 / XP SP3	AFPSPR7AS

Notes: 1) Windows is registered trademark or trademark of Microsoft Corporation in the United States and other countries.

2) When exporting to China, CPU unit without encryption function is required.

### Web screen creation tools

Product name	Descriptions	Part No.
Control Web Creator	Windows version. Downloadable free of charge from our website. Please purchase Key unit separately.	AFPSWC
Key unit	License key for Control Web Creator. 1 license. For USB port.	AFPSWCKEY

Key unit **AFPSWCKEY** 



\*Key unit is required to create Web content. You do not need Key unit to view Web content on a browser.

### **Motion control setting tools**

Product name	Descriptions	
Motion control setting tool Control Motion Integrator	Windows version. Downloadable free of charge from our website. Please purchase Key unit separately.	AFPSMTJP
Control Motion Integrator Key unit	License key for <b>Control Motion Integrator</b> . 1 license. For USB port. Please purchase <b>Control Motion Integrator</b> if you use it after 60 days since installing it.	AFPSMTKEY



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FP-X

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Applications

Software Program Transfer

FP-X0

FP0R FPΣ FP-X

FP2SH FP-e

### **Others**

Product name	Appearance	Descriptions	Part No.
End unit		Supplied with <b>FP7</b> CPU unit and expansion slave unit.	AFP7END
FP7 terminal block		Supplied with I/O unit and analog I/O unit with terminal block. (5 pieces)	AFP7TER
Discrete-wire connector set (40 leads)		Supplied with <b>FP7</b> input and output unit (MIL connector), high-speed counter unit, positioning unit and pulse output unit. (2 pieces)	AFP2801
Flat cable connector set (40 leads)		Supplied with <b>FP7</b> input and output unit (MIL connector), high-speed counter unit, positioning unit and pulse output unit. For simple connection using a flat cable. (2 pieces)	AFP2802
Multi-wire connector pressure contact tool		Necessary when wiring transistor output type connectors.	AXY52000FP
Motor driver I/F terminal II 1 shaft (Note)		Connectable MINAS series with FP7 positionning unit, pulse output unit,	AFP8503
Motor driver I/F terminal II 2 shafts (Note)	# # * * * * * * * * * * * * * * * * * *	FPΣ positionning unit, FP2 positionning unit (multi-function type)	AFP8504
MINAS A4 series / A5 series exclusive cable 1 m 3.281 ft			AFP85151
MINAS A4 series / A5 series exclusive cable 2 m 6.562 ft		Connectable MINAS A4 series / A5 series with motor driver I/F terminal II	AFP85152
Positioning connection cable 0.5 m 1.640 ft		Connectable FP7 positionning unit, pulse output unit, FP5 positionning	AFP85100
Positioning connection cable 1 m 3.281 ft		unit, FP2 positionning unit (multi-function type) with motor driver I/F terminal II	AFP85101

Note: Motor driver I/F terminal II (1 shaft and 2 shafts)

- Servo signal of **FP7** positioning unit and **FP7** pulse output unit can not be used. Please use the servo ON terminal of motor driver I/F terminal II.
- Timing input of FP7 pulse output unit can not be used.

### Pressure contact for multi-wire

Product name	Adapted cable size	Electric wire		Deat Ne	
		Coated diameter	Remarks	Part No.	
Pressure contact for multi-wire	AWG#22	91.0 to 91.1 mm	AWG#22: 12 wires / 0 .18 stranded wire	AXW7221FP	
	AWG#24		Stranded wire		
	multi-wire	AWG#26	ø1.3 to ø1.1 mm	Stranded wire	AXW7231FP
	AWG#28	ø0.051 in to ø0.043 in	Stranded wire	AAW/231FP	

### OPTIONS

### **Connector terminals**

### Connector terminals recommended for use with the FP7

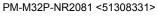
•WAGO Company of Japan, Ltd

Connector terminal parts numbers

- PM-M32P-NR2081 <51308331> (straight, poles: 40P, for **FP7** circuits)
- PM-M32P-2081 <51308332> (angled, poles: 40P, for FP7 circuits)
- IM-M2081-40PC-3A-FP <51308333> (angled, poles: 40P, one-to-one circuits)

### **Connector terminals**







PM-M32P-2081 <51308332> IM-M2081-40PC-3A-FP <51308333>

Cable parts numbers (MIL40P → MIL40P)

- PM-MM40SS-F1M <51227194> (Flexible cable)
- PM-MM40SU-F1M <51224816> (Flexible cable)
- PM-MM40SS-F1M-S <51255411> (Flexible cable / shielded)
- PM-MM40SU-F1M-S <51269259> (Flexible cable / shielded)
- PM-MM40SU-E1M <60254323> (Easy cable)

Notes: 1) With "SS" and "SU", the polar orientation of the cable is reversed on the PLC side MIL pole slot.

2) Please inquire for lengths other than 1 m 3.281 ft.



PM-MM40SS-F1M <51227194> PM-MM40SU-F1M <51224816> PM-MM40SU-E1M <60254323>

To learn more about connector terminals, please contact WAGO Company of Japan, Ltd http://www.wago.co.jp/

•TOYOGIKEN CO., LTD.

PCN7-1H40 (crimping terminal type, poles: 40P) Cable: KB40N-1H1H-\*MB (AWG28, unshielded)

\*Cable length (m ft): 0.5 1.640 / 1 3.281 / 1.5 4.921 / 2 6.562

To learn more about connector terminals, please contact TOYOGIKEN CO., LTD. http://www.togi.co.jp/en/



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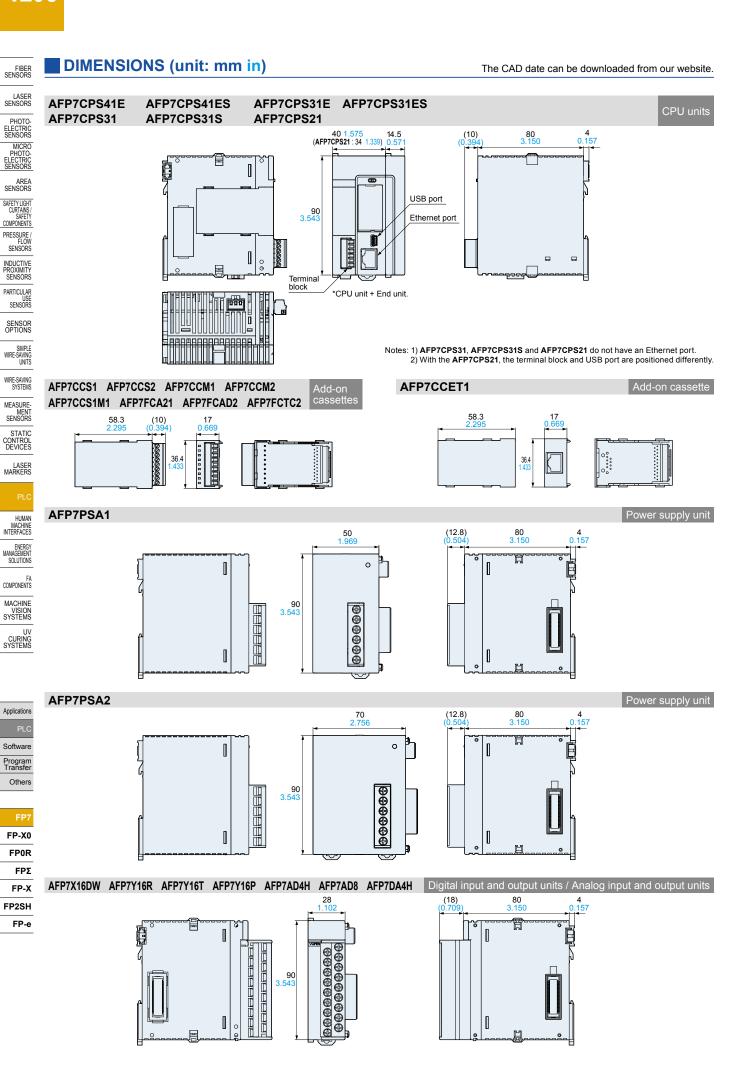
Others

FP-X0

FP0R

FPΣ FP-X

FP2SH

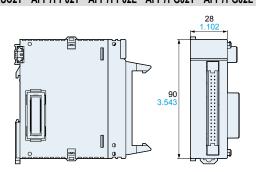


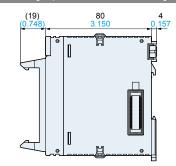
### DIMENSIONS (unit: mm in)

The CAD date can be downloaded from our website.

AFP7EXPM AFP7X32D2 AFP7Y32T AFP7Y32P AFP7MXY32DWD AFP7MXYDWDH AFP7HSC2T AFP7PP02T AFP7PP02L AFP7PG02L

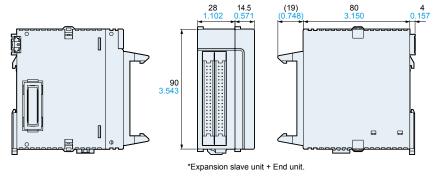
Expansion master unit / Digital input and output units / Multi input and output units / High-speed counter unit / Positioning units / Pulse output units





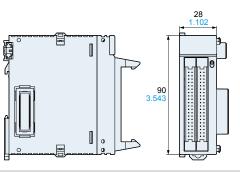
**AFP7EXPS** 

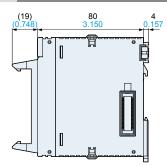
Expansion slave unit



AFP7X64D2 AFP7Y64T AFP7Y64P AFP7XY64D2T AFP7XY64D2P AFP7HSC4T AFP7PP04T AFP7PP04L AFP7PG04T AFP7PG04L

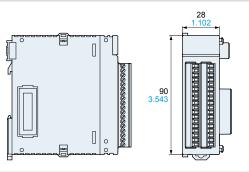
Digital input and output units / High-speed counter unit / Positioning units / Pulse output units

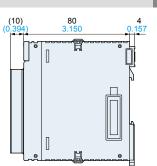




AFP7TC8 AFP7RTD8

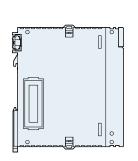
Temperature input units

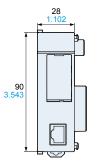


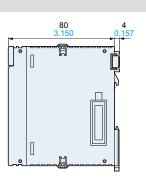


AFP7MC16EC AFP7MC32EC AFP7MC64EC

Motion control units







FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY LIGHT CURTAINS / SAFETY COMPONENTS PRESSURE / FLOW SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR USE SENSORS

SENSOR OPTIONS

SIMPLE WIRE-SAVING UNITS

SYSTEMS

MEASURE-MENT SENSORS

STATIC CONTROL DEVICES

LASER MARKERS

PLC

HUMAN MACHINE INTERFACES

SOLUTIONS

FA
COMPONENTS

MACHINE VISION SYSTEMS

UV CURING SYSTEMS

Applications

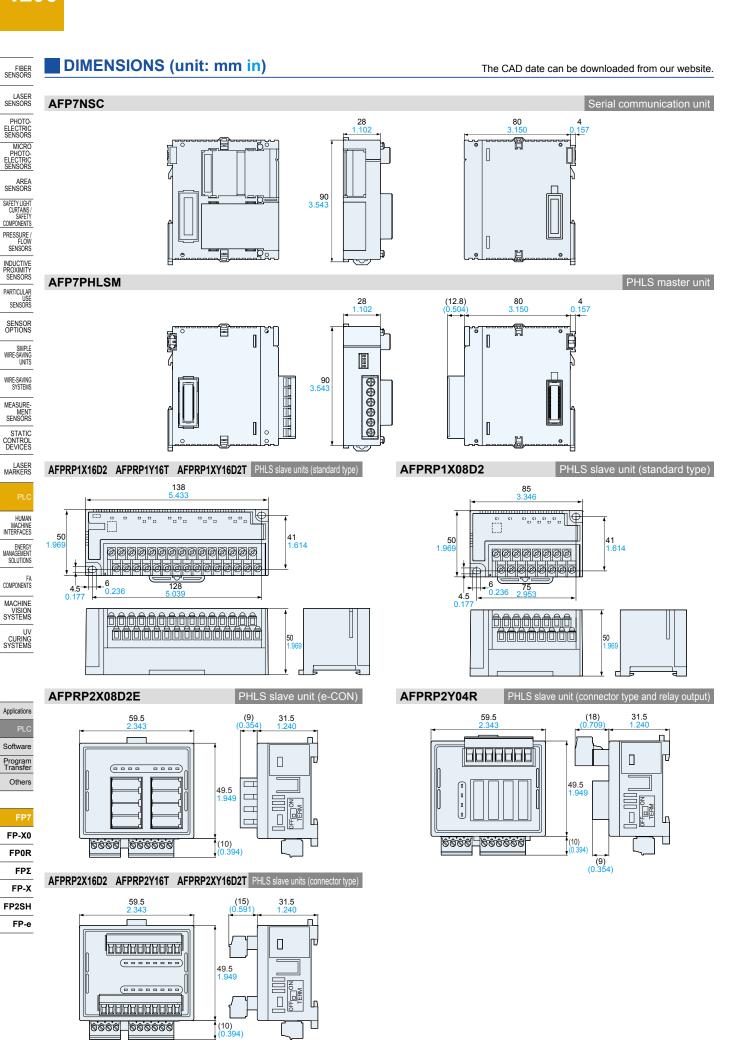
Software Program Transfer

FP-X0

FP0R FPΣ

FP-X

FP2SH FP-e



### MEMO

