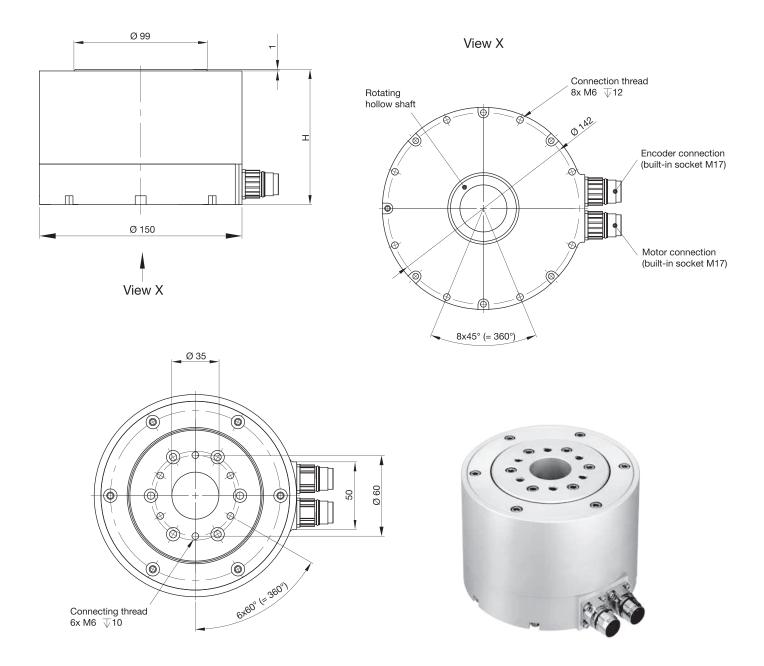
# HIWIN rotary tables

# 5. TMS1X HIWIN rotary tables

#### Dimensions of the TMS1X HIWIN rotary table

(for values, see Table 5.1)



## **Positioning Systems**

 Table 5.1 Specifications for HIWIN TMS1X Rotary Tables

## **Specifications for HIWIN Rotary Tables**

	Symbol	Unit	TMS12	TMS14	TMS16	TMS18
Peak torque for 1 second	$T_p$	Nm	12.5	25	37.5	50
Continuous torque (coil temp. 80°C)	T <sub>c</sub>	Nm	5	10	15	20
Stall torque (coil temp. 80°C)	$T_s$	Nm	3.5	7	10.5	14
Moment of inertia of rotating parts	J	kgm <sup>2</sup>	0.006	0.0065	0.007	0.0075
Mass	$M_{m}$	kg	5.7	7	8.3	9.5
Max. axial load	Fa	N	3700	3700	3700	3700
Max. radial load	$F_{r}$	N	1700	1700	1700	1700
Max. speed (at 400 V <sub>AC</sub> ) for 1 second	Nmax	rpm	1000	1000	1000	1000
Nominal speed (at 400 V <sub>AC</sub> and 30% DR)		rpm	500	500	500	500
Accuracy		arc sec	150	150	150	150
Repeatability		arc sec	6	6	6	6
Radial run-out		mm	0.03	0.03	0.03	0.03
Axial run-out		mm	0.03	0.03	0.03	0.03
Height	Н	mm	100	120	140	160
Protection class			IP40			

#### **Motor Specifications**

	Symbol	Unit	TMS12	TMS14	TMS16	TMS18		
Peak current for 1 second	I <sub>n</sub>	A <sub>eff</sub>	10	10	10	10		
Continuous current (coil temp. 80°C)	I <sub>c</sub>	A <sub>eff</sub>	4	4	4	4		
Motor constant (coil temp. 25°C)	K <sub>m</sub>	Nm/√W	0.66	1.02	1.29	1.64		
Coil resistance (coil temp. 25°C) 1)	R <sub>25</sub>	Ω	1.2	2	2.8	3.1		
Coil resistance (coil temp. 100°C) 11	R <sub>100</sub>	Ω	1.5	2.5	3.5	4.38		
Motor inductance 2)	L	mH	4.3	7.5	10.5	11.6		
Electric time constant	T <sub>e</sub>	ms	3.6	3.75	3.75	3.6		
Torque constant	$K_{t}$	Nm/A <sub>eff</sub>	0.91	2.5	3.75	5		
Voltage constant	$K_{v}$	V <sub>rms</sub> /(rad/s)	0.53	1	1.5	2		
Number of poles	2p	_	22	22	22	22		
Thermal resistance	$R_{th}$	K/W	0.52	0.74	0.55	0.5		
Thermal circuit breaker			Bimetal (break contact), switching point 100°C, 12 VDC/6 A, 24 VDC/3 A					
Max. intermediate circuit voltage		V	500	500	500	500		

<sup>1)</sup> Line resistance

## Encoder specifications (optical, incremental)

- O 3600 lines/cycle
- Index mark
- $\circ$  Signal output sin/cos 1  $V_{ss}$

<sup>&</sup>lt;sup>2]</sup> Line inductance